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Applicants : Mark Worthington et al.
For : METHODS AND APPARATUS FOR ANALYZING
OPERATIONAL AND NONOPERATIONAL DATA
ACQUIRED FROM OPTICAL DISCS

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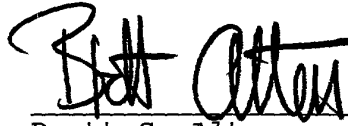
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METHODS AND APPARATUS FOR ANALYZING
OPERATIONAL AND NONOPERATIONAL
DATA ACQUIRED FROM OPTICAL DISCS

Field of the Invention

5 The present invention relates to methods and
apparatus for analyzing nonoperational data acquired by
reading optical discs, and in particular, by reading
trackable optical discs having concurrently readable
nonoperational structures. More particularly, the
10 methods and apparatus described herein may be used to
identify, discriminate, and classify patterns in the
data that report one or more physical properties of
nonoperational structures disposed upon or within an
optical disc. The invention also relates to methods
15 and apparatus for interpreting clusters of such
patterns and methods of mapping them according to
positional information present within the digital data.

Background of the Invention

20 In the two decades since the development of
audio compact discs, the progression of standards for
physically mastering data on optical discs has been
matched by a corresponding evolution in the logical
approaches to encoding the data. Thus, the progression

from single data layer discs with pits mastered along a continuous spiral to multiple data layer discs with zoned wobbled grooves has been matched by a corresponding evolution from the eight-to-fourteen modulation of CIRC-encoded digitized audio data to the sophisticated data encoding strategies established for DVD video and DVD-RAM.

Yet the disparate approaches to the logical encoding of data over the past two decades of optical disc evolution all share one fundamental characteristic: in each case, the data-encoding scheme is known at the time decoding must be effected; without such a predetermined encoding scheme, the decoding chipset could not thereafter accurately recreate the stored information. For readers or reader/writers that maintain backwards-compatibility with earlier standards, the chipset accommodates each (or at least a subset) of the earlier, prior-established, determinate encoding schemes.

Copending and commonly owned U.S. Patent Application Nos. 09/183,842 filed October 30, 1998, 09/311,329 filed May 14, 1999, and 60/134,368 filed May 14, 1999, incorporated herein by reference in their entireties, describe optical discs that possess concurrently readable nonoperational structures. During trackable reading of these novel discs, the nonoperational structures produce signals that are discriminably embedded within the normal operational electrical responses. These signals report physical properties of the nonoperational structures. As might be expected, however, the signals from the nonoperational structures so inspected match no pre-established encoding standard. There thus exists a need in the art for analytical methods, software, and devices that permit the signals produced by such nonoperational structures to be identified, analyzed,

and thereby decoded. More generally, there exists a need in the art for analytical methods, software, and devices that permit the post-acquisition decoding of signals acquired from optical media lacking a
5 predetermined encoding scheme.

Summary of the Invention

The present invention solves these and other problems in the art by providing methods and apparatus for analyzing data acquired by reading an optical disc
10 having at least one readable nonoperational structure, the methods and apparatus including the step of identifying patterns in the data that report a physical property of the nonoperational structure. The present invention particularly provides methods and apparatus
15 for analyzing data acquired by reading a trackable optical disc having at least one concurrently readable nonoperational structure.

It is also an object of this invention to provide methods and apparatus for analyzing data
20 generated by reading an optical disc having a plurality of physically nonidentical readable nonoperational structures, by identifying patterns in the data that distinguish among the physically nonidentical nonoperational structures. The present invention
25 particularly provides methods and apparatus for analyzing data acquired by reading a trackable optical disc having a plurality of physically nonidentical nonoperational structures readable concurrently with the disc's tracking attributes.

30 It is a further object of this invention to provide methods and apparatus for determining the relative physical locations of two different nonoperational structures on a surface of an optical disc by identifying in the data acquired from reading
35 the disc (i) a first pattern that reports a physical

property of the first nonoperational structure and
(ii) a second pattern that reports a physical property
of the second nonoperational structure, and then
calculating at least relative physical locations of the
5 first and second nonoperational structures on the disc.

It is yet a further object of this invention
to provide methods and apparatus for mapping the
physical locations of nonoperational structures on a
surface of an optical disc by: (1) determining a
10 relative physical location of at least one of the
nonoperational structures; and (2) marking a
representation of the surface of an optical disc with
at least one object that indicates the at least one
relative physical location.

15 It is yet another object of this invention to
provide methods and apparatus for classifying an object
having at least one sub-centimeter dimension by
identifying, in the data acquired by reading an optical
disc upon or within which the object is disposed as a
20 nonoperational structure, a pattern that reproducibly
distinguishes the object. It is particular object to
provide such methods and apparatus for classifying an
object that is disposed upon or within a trackable
optical disc as a nonoperational structure concurrently
25 readable with the disc's tracking attributes.

It is another object of this invention to
provide methods for analyzing data comprising
retrieving data acquired from an optical disc,
particularly a trackable optical disc, with readable
30 nonoperational structures; analyzing the data;
generating at least one result object; and outputting
the result object.

It is yet another object of this invention to
implement the methods of the present invention on
35 computer systems.

It is yet another object of this invention to provide a computer readable medium (e.g., storage and transmission media) containing nonoperational data acquired from an optical disc, particularly from a trackable optical disc containing nonoperational structures concurrently readable with the disc's tracking attributes. In one embodiment of this aspect of the invention, the data includes patterns that can be mapped according to positional information present on the digital data. In a further embodiment, the data includes at least one result object that indicates the position of at least one of the nonoperational structures detected on a surface of said disc.

It is yet another object of this invention to provide a computer readable medium (e.g., storage and transmission media) containing instructions for analyzing data according to any of the methods of the present invention, and a particular object to provide a computer readable medium containing instructions for identifying patterns in the data that report a physical property of at least one nonoperational structure disposed in or upon the disc.

It is yet another object of this invention to provide a system for analyzing data acquired from an optical disc having at least one nonoperational structure, the system comprising a computer capable of retrieving the data, analyzing the data, generating at least one result object, and outputting the result object.

It is yet another object of this invention to provide a system for remotely analyzing data acquired from an optical disc having at least one nonoperational structure in order to expedite complex data analysis and reporting the results thereof. In one embodiment of this aspect of the invention, the system includes a client computer capable of acquiring data from a

trackable optical disc with concurrently readable
nonoperational structures, and transmitting the data
over a remote connection; and a server computer capable
of receiving the data over the remote connection,
5 analyzing the data, and generating at least one result
object from the data.

It is yet another object of this invention to
provide a visual display of at least one software-
generated object, wherein the object reports at least
10 one physical property of a nonoperational structure of
an optical disc. In one embodiment of this aspect of
the invention, at least one of the displayed properties
is the position of the nonoperational structure on said
disc. In yet another embodiment, the displayed
15 property is the size, in at least one dimension, of
said nonoperational structure, such as in the disc's
tangential direction.

Brief Description of the Drawings

The above and other objects and advantages of
20 the invention will be apparent upon consideration of
the following detailed description, taken in
conjunction with the accompanying drawings, in which
like reference characters refer to like parts
throughout, and in which:

25 FIG. 1 is a flow chart of steps for carrying
out an illustrative embodiment of a method of the
present invention, showing an overview of data analysis
process 10 according to this invention;

FIG. 1a shows a system for remotely analyzing
30 data according to this invention, which includes a
server computer, at least one client computer, and an
Internet connection, according to this invention;

FIG. 2 is a flow chart of steps for carrying
out an illustrative embodiment of a method for
35 retrieving data according to step 13 of FIG. 1;

FIG. 3 is a flow chart of steps for carrying out an illustrative embodiment of a method for analyzing data records and creating result objects according to step 22 of FIG. 2;

5 FIG. 3a shows a data pattern that can be found in a typical data record acquired by reading an optical disc according to this invention;

 FIG. 3b shows another data pattern that can be found in a typical data record acquired by reading
10 an optical disc according to this invention;

FIG. 4 is a flow chart of steps for carrying out an illustrative embodiment of possible decoding process 40 according to any of steps 37a, 37b, ..., 37n shown in FIG. 3, where n is an integer;

15 FIG. 5 is a flow chart of steps for carrying out illustrative process 50 of outputting one or more result objects according to step 16 of FIG. 1;

 FIG. 6 is a flow chart of steps for carrying out an illustrative embodiment of process 50 according
20 to this invention;

 FIG. 7 is a flow chart of steps for carrying out process 70, which is an illustrative embodiment for outputting a map chart (and an optional trace chart) according to step 16 of FIG. 1, step 54 of FIG. 5, or
25 step 61 of FIG. 6 of this invention;

 FIG. 8 shows an illustrative embodiment of initial graphical user interface screen 100 according to this invention;

 FIG. 8a shows an illustrative embodiment of
30 panel 140 shown in initial graphical user interface screen 100 of FIG. 8 according to this invention;

 FIG. 8b shows an illustrative embodiment of panel 150 shown in initial graphical user interface screen 100 of FIG. 8 according to this invention;

FIG. 8c shows an illustrative embodiment of panel 180 shown in initial graphical user interface screen 100 of FIG. 8 according to this invention;

FIG. 9 shows an illustrative embodiment of
5 debug information panel 180 according to this invention;

FIG. 10 shows an illustrative embodiment of a map chart displayed according to this invention;

FIG. 11a shows a zoomed region of the same
10 map chart shown in FIG. 10 according to this invention;

FIG. 11b shows a zoomed region of a map chart including seven clusters, each of which includes three or four distinct features according to this invention;

FIG. 12 shows an illustrative embodiment of a
15 graphical user interface with a histogram chart according to this invention;

FIG. 13 shows an illustrative embodiment of a graphical user interface with a jitter chart, according to this invention;

FIG. 14a shows an illustrative embodiment of
20 a graphical user interface, including a map chart, according to this invention;

FIG. 14b shows an illustrative embodiment of a printer panel for use in a graphical user interface
25 according to this invention;

FIG. 15 shows an illustrative embodiment of a graphical user interface, including another map chart, according to this invention;

FIG. 16 shows an illustrative embodiment of a
30 graphical user interface, including yet another map chart, according to this invention;

FIG. 17 shows an illustrative embodiment of a graphical user interface, including still another map chart, according to this invention;

FIG. 18 shows an illustrative embodiment of a graphical user interface, including a further map chart, according to this invention;

FIG. 19 shows an illustrative embodiment of a graphical user interface, including yet a further map chart, according to this invention;

FIG. 20 shows an illustrative embodiment of a graphical user interface, including a map chart and a trace chart, according to this invention;

FIG. 21 shows a two-dimensional composite light microscopic image of the laser proximal surface of a trackable disc with $2.8\mu\text{m}$ spheres electrostatically adherent to the metalized surface and manually aligned substantially along a wobbled groove, according to this invention;

FIG. 22 shows a higher magnification light microscopic image of a portion of the same disc as shown in FIG. 21 according to this invention;

FIG. 23 shows a trace chart displaying a single electrical response reported in the buffered HF signal during reading along a single one of the wobble tracks that passes through the area of the disc shown in FIG. 22, according to this invention;

FIG. 24 shows a trace chart displaying multiple electrical responses reported in the buffered HF signal along four of the wobble tracks that pass through the area of the disc shown in FIG. 22, with the track shown in FIG. 23 appearing as the second track from the top, which have been aligned in X-axis registration, according to this invention;

FIG. 25 shows a trace chart displaying multiple electrical responses reported in the buffered HF signal along six of the wobble tracks that pass through the area of the disc shown in FIG. 22, which have been aligned in X-axis registration, according to this invention;

FIG. 26 shows a trace chart displaying multiple electrical responses reported in the buffered HF signal along ten of the wobble tracks that pass through the area of the disc shown in FIG. 22, which have been aligned in X-axis registration, according to this invention;

FIG. 27 shows a map chart of a portion of the disc shown optically in FIGS. 21-22 and electrically, by means of trace charts, in FIGS. 23-26, according to this invention;

FIG. 28 shows a map chart of the same disc shown optically in FIGS. 21-22 and electrically in FIGS. 23-26, at lesser zoom than in FIG. 27, according to this invention;

FIG. 29 shows a map chart of the same disc shown optically in FIGS. 21-22 and electrically in FIGS. 23-26, at lesser zoom than in FIG. 28, according to this invention;

FIG. 30 shows a map chart of the same disc shown optically in FIGS. 21-22 and electrically in FIGS. 23-26, at lesser zoom than in FIG. 29 and with the acquired digital data, shown boxed, mapped to a representation of an optical disc, according to this invention;

FIG. 31 shows a map chart of the same disc shown optically in FIGS. 21-22 and electrically in FIGS. 23-26, at still lesser zoom than in FIG. 31, according to this invention;

FIG. 32a is a light microscope image of the metal surface of a trackable optical disc, showing an aggregation on the disc's metal surface of beads of disparate size and composition, according to this invention;

FIG. 32b is a trace chart aligning, in X-axis registration, the electrical responses reported in the buffered HF signal along ten of the tracks that pass

through the region of the disc shown photographically in FIG. 32a, according to this invention;

FIG. 33 shows an illustrative embodiment of another map chart displayed according to this
5 invention;

FIG. 34 shows a trace chart displaying a single electrical response reported in the buffered HF signal during reading along a single one of the wobble tracks that passes through the area of the disc shown
10 in FIG. 33, according to this invention; and

FIG. 35 shows an image chart that corresponds to the wobble tracks that pass through the boxed area of the disc shown in FIG. 33, according to this invention.

15 Detailed Description of the Invention

In order that the invention herein described may be fully understood, the following detailed description is set forth. In the description, the following terms are employed.

20 As used herein, the term "radial" denotes, in the plane of one or more of a disc's data-encoding surfaces, the direction forward or backward along a tracking spiral. A disc surface, according to this invention, can be an internal or external surface.

25 As used herein, the term "tangential" denotes, in the plane of one or more of a disc's data-encoding surfaces, the direction inward or outward along a line drawn from the disc's physical center to its outer circumference.

30 As used herein, the phrase "radial plane" refers to the plane in which a disc's tracking (e.g., spiral tracking) features are disposed, and is the plane of one or more of the disc's data-encoding surfaces.

As used herein, the term "nonoperational structure" means any structure on or within an optical disc that is capable of producing a signal when the disc is read by an optical disc reader, the signal of which, however, is not required (although possibly useful) for drive operation during reading. Nonoperational structures include, for example, analyte-specific signal elements, as described immediately below.

As used herein, the term "analyte-specific signal element" refers to any nonoperational structure that may be used to signal the presence of a specific analyte in a sample applied to an optical disc. The term thus includes, *inter alia*, such signal elements as are exemplified herein — including beads — as well as those that are described in copending and commonly owned U.S. Patent Application Nos. 08/888,935 filed July 7, 1997, 09/120,049 filed July 21, 1998, 09/183,842 filed October 30, 1998, and 09/311,329 filed May 14, 1999, the disclosures of which are incorporated herein by reference in their entireties. The term includes both those structures that are alone detectable by an optical disc reader and those that require additional components to be rendered detectable.

As used herein, the term "turn" denotes a 360° arc of a spiral track of an optical disc.

Copending and commonly owned U.S. Patent Application Nos. 09/183,842 filed October 30, 1998, 09/311,329 filed May 14, 1999, and 60/134,368 filed May 14, 1999, which are incorporated herein by reference in their entireties, describe optical discs that possess concurrently readable nonoperational structures. During trackable reading of these novel discs, the nonoperational structures produce signals that are discriminably embedded within the normal

operational electrical responses; the embedded signals report physical properties of the nonoperational structures. Using such discs, the routine process of optical disc reading is transformed into a scanning
5 laser microscopic inspection of one or more of the disc's surfaces, and the disc drive into a scanning confocal laser microscope. Other approaches to the optical interrogation of nonoperational structures disposed on rotating disc surfaces, using modified
10 optics, have also been described (see, e.g., U.S. Pat. No. 5,892,577; EP 0417305A; and WO 97/21090).

The signals generated by the nonoperational structures, however, match no established optical disc data encoding standard.

15 The nonoperational structures exemplified in copending and commonly owned U.S. Patent Application Nos. 09/183,842, filed October 30, 1998, 09/311,329 filed May 14, 1999, and 60/134,368 filed May 14, 1999, include human red blood cells and spheres.

20 Although the outer diameter of the spheres used in the examples of this invention is typically on the order of microns (i.e., μm), it will be appreciated that a wide range of sizes can be detected and characterized according to this invention. Thus, a
25 nonoperational structure can be almost any structure of sufficient size to be detectable — with commercially-available optical disc readers, presently about 1/2 the incident laser wavelength — yet not so large as to interrupt tracking, focus, speed control, or
30 synchronization. The protean nature of such structures — the extraordinary range in permissible size, reflectivity, absorbence, and shape — creates an enormous diversity in resulting signal patterns.

Furthermore, such nonoperational structures
35 will often be stochastically, rather than determinatively, distributed on the surface of the

disc; the location of the relevant signal patterns will often not be known in advance. There thus exists a need in the art for analytical methods, software, and devices that can recognize, discriminate, and classify
5 a wide variety of patterns distributed randomly throughout the digital data sample.

Many of the nonoperational structures to be detected by optical inspection of such discs will be sufficiently large as to cross at least two adjacent
10 tracks, producing patterns discontinuously in the digital data stream. In other words, a single structure located on or within a disc can produce data features at positions that are about 360° apart on a spiral track of the optical disc. In this, case, the
15 discontinuity in the data between the two data features can report a physical property of the structure in the tangential direction.

Notwithstanding existing deinterleaving algorithms, no optical disc decoding scheme has
20 contemplated assembling discontinuous data according to the tangential locality of the data on the physical disc surface. Accordingly, there exists a need for methods and apparatus for effecting such decoding of data.

25 More generally, the physical location of digitally-encoded data on optical discs is of significance under existing standards principally as it affects the operational necessities of the reading process, and in particular, as it implicates access to
30 the data during reading. Once the data are read and decoded, the physical location that the data had occupied on the disc becomes irrelevant: during execution of program instructions read from CD-ROM, for example, the computer's CPU is indifferent to whether
35 the program had originally been stored on the first or last track of the disc.

In contrast, the use of an optical disc reader as a scanning laser confocal microscope can make the original physical location of detected structures of enduring relevance during analysis.

5 For example, as noted above, the physical location of one or more detected structures can be used to identify radial and tangential dimensions of the underlying structure.

10 Additionally, the physical location of the detected structure is relevant to the analysis and interpretation of analyte-specific assays that are disposed on the disc in deliberate geometric patterns. Copending and commonly owned U.S. Patent Application Nos. 08/888,935 filed July 7, 1997, and 09/120,049
15 filed July 21, 1998, describe analytical assay geometries in which the absolute and/or relative physical locations of nonoperational structures can report, inter alia, the identity of the sample, the identity of the probe, the identity of the analyte, and
20 the concentration of analyte.

There thus exists a need for methods and apparatus for mapping data patterns produced by one or more nonoperational structures (e.g., a cluster of such structures) according to positional information present
25 within the digital data sample.

The present invention solves these and other problems in the art by presenting methods and apparatus for analyzing nonoperational data acquired from optical discs. The methods and apparatus are particularly
30 useful in analyzing nonoperational data acquired from trackable optical discs having concurrently readable nonoperational structures.

FIG. 1 shows an overview of data analysis process 10 that can be performed on a computer system
35 according to this invention.

In step 11, program parameters are initialized. As used herein, program parameters include, but are not limited to, memory allocation parameters, form parameters, which are used in the program's graphical user interface (e.g., default parameters used in windows-based programs), and object parameters, which are associated with simple or composite result objects (described below). In an embedded, real-time form of this invention, the overall environment could also be initialized. Various result object types, which are discussed below, may be used by one or more (including all) program forms according to this invention. Program parameter initialization is optional and its necessity may depend on the particular programming environment used to implement this invention.

After initialization, data are retrieved from a data source in step 13. A data source can either be specified by a user or defined by the program itself. A data source according to this invention can be direct data source 12, which may provide a substantially continuous data stream, or stored data source 17, which may provide a previously stored data file.

Direct data source 12 can be a local or remote optical disc drive (i.e., reader) capable of reading data for subsequent retrieval and use according to this invention. If remote, direct data source 12 can be connected to a computer programmed according to this invention via the Internet or any other network-type connection. Direct data can also be provided through an auxiliary device (connected to a drive), such as a conventional analog-to-digital converter, or a customized equivalent thereof. A computer programmed to retrieve direct data in step 13 could be synchronized with a computer programmed to acquire data. An example of how data can be acquired and

retrieved according to this invention is described in U.S. Patent Application No. 09/183,842, filed October 30, 1998, which is hereby incorporated by reference in its entirety.

5 In order to selectively acquire data from any portion of an optical disc (e.g., the portion with nonoperational structures disposed thereon), physical synchronization markers can be used, as described more fully in Worthington et al. U.S. Patent Application
10 No. 60/____, filed concurrently herewith, entitled "Methods and Apparatus for Optical Disc Data Acquisition Using Physical Synchronization Markers" (Attorney Docket No. BURST-18 P), which is hereby incorporated by reference in its entirety.

15 FIG. 1a shows a system for remotely analyzing data according to this invention, which includes server computer 2 and at least one client computer 3. In a preferred embodiment, client computers 3 and server 2 are coupled using a remote connection, such as Internet
20 connection 1. Remote analysis by server 2 could be particularly useful when analysis requires complex computations that not easily handled by client computer 3, such as when complicated image analysis must be performed. Preferably, client computer 3 is
25 capable of acquiring data from a trackable optical disc (e.g., using a direct source) with concurrently readable nonoperational structures, and transmitting the acquired data across the remote connection. Server computer 2 should also be capable of receiving the data
30 over the remote connection, analyzing the data, and generating at least one result object from the data. The result object is then optionally transmitted back to client computer 2 over the same or a different network connection.

35 As previously described, data according to this invention can be operational, nonoperational, or a

combination thereof. When operational and nonoperational data are retrieved separately the data can be merged when certain operational structures (e.g., that indicate sample number or track position) are useful for determining the position or identity of the nonoperational features in the data.

Multiple signals may be combined to form a single digital data set. For example, one may combine multiple analog signals to form a single combined analog signal and then quantize the combined analog signal to form the data. Alternatively, the method may involve quantizing each of the analog signals to form individual digitized data sets and then combining the individual digitized data sets to form a combined digitized data set.

Stored data source 17 is any data storage device capable of storing data for use by a computer programmed according to this invention. Like direct data source 12, stored data source 17 can be connected by any convenient connection means, including the Internet or any other network connection.

After data are retrieved in step 13, data are analyzed and one or more result objects are created in step 14. Result objects characterize operational and/or nonoperational features that appear in the data for subsequent output (e.g., displayed, printed, and/or saved) and for use by a local or remote user or process. Result objects can be of varying complexity and may include any number of features. For example, a simple result object could characterize a single nonoperational feature. Alternatively, a composite result object could characterize multiple operational and/or nonoperational features. Also, as described in more detail below, multiple processes can be used in combination to create a single result object.

After result objects are created in step 14, result objects can be output for subsequent use in step 16. Then, a user or process may retrieve additional or different data or may quit process 10 in
5 step 18.

FIG. 2 is a flow chart of steps for carrying out an illustrative embodiment of a method for retrieving data according to step 13 of FIG. 1. In this embodiment, data (e.g., a digital sample) are
10 retrieved in data records. A data record can include any convenient number of data items, and may be a subset or the entire data set. A single data record can contain any number of data items, but typically contains between 1 and about 10^9 data items, and more
15 typically between 1 and about 10^6 data items. Data records of the same or differing sizes may be retrieved during step 13. A data item can include one or more time-varying data points. Because time t and track position x are related by the linear velocity v of the
20 track being read during data acquisition,

$$x = v(x,t)t,$$

time-varying data can also be represented as position-varying data.

In step 21, at least one data record is
25 retrieved from data source 12 or 17. The data source may be specified by a user, an external process, or the source may be predetermined. After step 21, the data record is analyzed and one or more result objects may be created in step 22. As described more fully below
30 with reference to FIGS. 3 and 4, a result object is normally created when a feature of interest is identified in the record. Alternatively, a blank object may be created if no such feature is identified. Analysis in step 22 may use one or more data records

(i.e., at least a current data record and possibly one or more previously stored data records). Creation in step 22 may create one or more result objects. Result objects created may be stored (e.g., in a record history) as they are created or accumulated and stored later in step 23. Result objects may also be transmitted or relayed to other processes as needed.

In step 24, it is determined whether the data record processed in steps 21-23 is the last data record of the data set. If it is the last record, control of the process may be returned to a higher level (e.g., step 14 of FIG. 1). On the other hand, if it is determined that the record is not the last, steps 21-23 can be repeated, as necessary.

FIG. 3 is a flow chart of steps for carrying out an illustrative embodiment of a method for analyzing data records and creating result objects according to step 22 of FIG. 2. In this embodiment, data records are analyzed by processing individual data items. In the context of the discussion that follows, and only for the purpose of simplification, a data item refers to a single data point.

In step 31, a data item is retrieved from a data record previously retrieved in step 21. Next, in step 32, it is determined whether that data item is operational or nonoperational. A nonoperational data item is any data item that corresponds to a nonoperational structure. In contrast, an operational data item is a data item that corresponds to an operational structure required or useful for drive operation during reading, such as embedded control and command structures, tracking information structures (e.g., track number, track start and track end), address information structures (e.g., absolute address and relative address), disc speed indicating structures, end of data structures, etc. In the

context of CD-ROM, CD-R, and DVD's, for example, some operational structures can be nonoperational (e.g., see U.S. Appl. No. 60/____,____ (Atty. Doc. No. BURST-18 P)).

First, a lead was attached to tap the
5 nonequalized HF output of the drive. The analogue HF signal was buffered with a unity gain amplifier and input to an ULTRAD-1280 dual 40 MHZ 12 bit A/D PCI data acquisition board (Ultraview Corporation, Orinda, CA) installed, with its own bundled software, in a second
10 Pentium® processor-based personal computer (the "data" computer). In Example 3, described briefly above and in detail below, the HF signal was fed in real time to a digital oscilloscope to generate the tracings shown in FIGS. 13-18. The ULTRAD data acquisition board
15 permits the analogue signal to be sampled, digitized, and written as a bit stream to a binary file on the computer's hard disk, thereafter to be interpreted by software.

In a second modification, a photodiode was
20 inserted into the drive in a position that permitted the diode to interrogate the disk edge during disk rotation. The diode signal was output to the triggering port of the ULTRAD 1280.

This latter modification is not necessary to
25 the practice of the present invention. At a 40 MHZ sampling rate, however, with 12 bits per sample, the data storage needed to record the entire assay disk (74 minutes at 1X speed) would be unwieldy, if not prohibitive. Thus, as described in detail in the
30 Example below, a triggering mark was painted on the edge of the assay disk assembly at a location rotationally earlier than the assay site itself. With each rotation, the photodiode would detect the triggering mark and trigger data acquisition by the
35 sampling card; the duration of sampling, controlled by software, was less than a full rotation, resulting in

data files of somewhat more manageable size. As further discussed below, real-time filtering based on image-recognition algorithms that direct storage of preferred data is an alternative, and oft preferred, means of reducing data file size.

If it is determined in step 32 that the data item is operational, it may be determined in step 33 whether the operational data item is the last data item in the record (e.g., an end of data marker). If the number of data items contained in the data record is known, one way that this determination can be made is by counting the data items retrieved in step 31 and comparing the count with the known number. Another way to make this determination is by decoding one or more identifying bits (i.e., a logical synchronization marker) that may be contained within or adjacent to the data item. Yet another way to make this determination is by use of a physical synchronization marker (i.e., an "end of data" marker), as described more fully in U.S. Patent Application No. 60/____,____, filed concurrently herewith (Attorney Docket No. BURST-18 P), which is hereby incorporated by reference herein. If the data item is determined to be the last item in the record, control of the process can be returned to a higher level via step 36. Although FIG. 3 shows step 33 after step 32, it will be appreciated that the determination made in step 33 can be made at any time during process 30, including before step 32.

If the operational data item is not the last data item, further processing may be desirable according to this invention. In step 35, for example, the data item could be identified and identification information could be stored for subsequent use by one or more nonoperational data decoding processes (e.g., any of the processes used in steps 37a, 37b, ..., 37n, where n is an integer). Accordingly, in step 39, one

or more of processes 37a, 37b, ..., 37n could be notified that the information is available.

If the data item retrieved in step 31 is determined to be nonoperational in step 32, its position parameter can be updated (e.g., incremented) in step 34. The position parameter reflects the position of the structure on the disc. In one embodiment, the position parameter is a radial position along a particular track of the optical disc. Once the position parameter is updated, the nonoperational data item can be processed by one or more nonoperational decoding process 37a, 37b, ..., 37n. Although FIG. 3 arranges these processes in series, it will be appreciated that they could also be arranged in parallel, or in a combination. One or more of these processes can be used to decode nonoperational data items in a predetermined or data-dependent sequence.

FIG. 4 is a flow chart of steps for carrying out an illustrative embodiment of possible decoding process 40 according to any of steps 37a, 37b, ..., 37n shown in FIG. 3.

As discussed above, the data items processed according to process 40 correspond to time- or position-varying data points that represent a varying amount of returned optical energy. As shown in trace chart 172 of FIG. 20, five sets of position-dependent track data are selected and plotted between radial track positions $-850\text{ }\mu\text{m}$ and $-820\text{ }\mu\text{m}$. The amplitude in the middle three data sets varies substantially at radial positions between about $-835\text{ }\mu\text{m}$ and $-825\text{ }\mu\text{m}$. As described above, certain amplitude variations are believed to be due to the presence of nonoperational structures (e.g., analyte-specific signal elements) on the surface of or contained within the optical disc (e.g., an external or internal surface). The process shown in FIG. 4, then, characterizes these amplitude

variations by measuring their width measured above or below a given amplitude threshold. As used herein, the term "width" refers to the time period, or equivalently the radial distance along a track, that the amplitude
5 remains above (or below, depending on the sign of the signal) the amplitude threshold. After the width of a data feature is measured, the width can be used to determine the type of underlying structure (e.g., whether the structure is an analyte-specific signal
10 element or a dust particle), such as by comparing the width to one or more previously identified width values. Such values can be stored in a computer database for automated comparison.

Other characterization methods that can be
15 used in accordance with this invention are Fourier analysis, auto-correlation, and masking.

Returning to process 40, it is determined, in step 43, whether program parameter INWINDOW is true or false. INWINDOW reflects whether the amplitude of a
20 data item satisfies one or more threshold criteria (e.g., is greater or less than an amplitude threshold). Preferably, INWINDOW has a default value of false. In the discussion that follows, when INWINDOW is false, it means that the amplitude of the previously processed
25 data item was less than the amplitude threshold. If INWINDOW is true, it means that the amplitude of the previously processed data item was greater than the amplitude threshold. It will be appreciated that the possible values of INWINDOW could have opposite
30 meanings. See, for example, the discussion of trace chart 172 of FIG. 20, where amplitude thresholds are shown below the baseline, or background level, of each trace.

If INWINDOW is determined to be false in
35 step 43, it is next determined in step 46 whether the current data item has an amplitude that is greater or

less than the amplitude threshold. If the amplitude is greater than the amplitude threshold, INWINDOW is set to true and one or more result objects are created. Each result object can be initialized to include

5 positional information, such as the tangential and radial position of the current data. A result object may also include raw data (e.g., one or more data points), quality indicators, structure types, etc. After one or more result objects are created in step

10 49, control of the process can be returned to a higher level by ending process 40 in step 44 to retrieve another data item. If the amplitude of the item is determined in step 46 to be less than the amplitude threshold, control can be returned to a higher level by

15 ending process 40 in step 44.

It will be appreciated that the amplitude threshold could be positive or negative, depending on the sign of the feature of interest.

For example, as shown in trace chart 172

20 shown in FIG. 20, position-dependent signal 174 includes substantially flat portions 175 and 176 and may include one or bumps and/or dips 177. Although dependent upon the nature of the original data acquisition and storage, a dip typically indicates a

25 decrease in the amount of returned light. To detect such a dip, amplitude threshold 178 preferably has a sign that is the same as the dip and a magnitude that is less than or equal to the dip amplitude (as measured from the flat background portion of the signal). A

30 signal refers to any electrical analog signal generated by a photodetector, or the like, in response to receiving light, and includes, for example, signals derived from a high frequency ("HF") signal, a tracking error signal, a focus error signal, and any combination

35 thereof.

When a data item crosses the amplitude threshold, the trace chart may reflect that cross by including a visual element (such as bar 179).

Conversely, a bump typically indicates an
5 increase in the amount of returned light. As explained more fully below, it is believed that a bump (i.e., an above-baseline signal) may be generated, for example, when a transmissive bead acts as a lens to further focus the incident laser light during reading. To
10 detect a bump, the amplitude threshold preferably has a sign that is the same sign as the bump and a magnitude that is less than or equal to the bump amplitude. As explained above, the sign used to plot the data is arbitrary and could be reversed.

15 It will further be appreciated that sets of thresholds and/or windows could be used to distinguish data features, particularly when the data features are more complex, such as those shown in FIG. 32b.

For example, if one class of nonoperational
20 data features is known to correspond to data pattern 38a, which includes a combination of two dips of widths W_1 and W_2 separated by distance D_1 , that combination can be detected as follows (see FIG. 3a). In a first step, any dips in the data could be
25 identified and stored with their measured widths and position parameters. In a second step, pairs of dips that are separated by distance D_1 and having widths substantially equal to W_1 and W_2 could be selected from all of the identified dips. In another step, the
30 selected pairs could be counted or used for further processing.

An example of further processing could include further distinguishing the selected pairs into subclasses using additional criteria, such as slope of
35 the signal between the dips or the shape of one or both of the dips. For example, as shown in FIG. 3b, data

pattern 38b includes a combination of two dips of widths W3 and W4 separated by intermediate distance D2. Some of the data within segment D2 has a deviation that is significantly greater than the data within
5 segment D1. As discussed above, pattern 38b could be detected using an algorithm described above with appropriate threshold criteria. In order to detect the difference between data patterns 38a and 38b, the maximum deviation H of the data within segment D2 can
10 be measured using additional threshold T3, as shown in FIG. 3b, or using any other reference point, such as the baseline. Alternatively, the difference between data patterns 38a and 38b can be detected by measuring width W5 using threshold T3. It will be appreciated
15 that the amplitude deviations measured in FIGS. 3a and 3b use a threshold different from the baseline, those deviations can also be measured from any reference point, including the baseline.

Further processing could also involve
20 analyzing a combination of previously selected data patterns (i.e., a cluster of data features) to determine whether that combination has any reportable property.

This method could also include varying the
25 amplitude threshold and measuring W1, W2, and D1 at different threshold values until an optimal threshold value is obtained. In this way, a more accurate count of the nonoperational features, and therefore the corresponding nonoperational structures, can be made.

30 These and other algorithms could be stored in a computer database for identifying and classifying detected operational and/or nonoperational data features (e.g., patterns). Therefore, it is a further aspect of this invention to provide a system that
35 includes a computer for processing data according to these identification (i.e., decoding) algorithms and a

computer database containing a plurality of these algorithms. The computer can be programmed to run one or more of these algorithms, as desired, to identify one or more nonoperational features and then to report
5 the results of the identification to a user.

Returning to FIG. 4, where only a single amplitude threshold is used, if INWINDOW was determined to be true in step 43, it is next determined in step 45 whether the current data item meets the selection
10 criteria (e.g., whether the amplitude of the current data item is greater than the amplitude threshold). If the criteria are met, one or more previously created result objects can be updated in step 48 to reflect this determination. Once updated, control can be
15 returned to a higher level by ending process 40 in step 44.

If the criteria are not met in step 45, further processing is necessary. When the criteria are not met, the underlying structure no longer provides a
20 sufficiently strong signal. Therefore, in step 47, INWINDOW is reset to false and a WIDTH of the underlying structure (e.g., an analyte-specific signal element) can be calculated (e.g., in units of time or distance). It will be appreciated resetting INWINDOW
25 to false in step 47 could occur at any time before ending in step 44.

In step 41, it is determined whether the value stored in WIDTH meets predefined width criteria. This determination is usually made by comparing WIDTH
30 with one or more time- or position-dependent thresholds. For example, this determination could be based on whether WIDTH is greater and/or less than one or more width thresholds. Typically, a minimum acceptable width and a maximum acceptable width are
35 used together to define a range (i.e., window) of

acceptable widths. The width criteria can be selected by the user or by an internal or external process.

If WIDTH meets the width criteria in step 41, one or more of the current result objects can be closed
5 and stored in step 41a. At this point, result objects could be transmitted, posted, or stored for subsequent use or processing.

If the value stored in WIDTH does not meet the width criteria in step 41, current result objects
10 can be deleted in step 41b (or closed and stored for subsequent analysis). Operational data can be stored in result objects as well. After the current result objects are closed, stored, and/or deleted in steps 41a and 41b, WIDTH can be reset to a default value (e.g.,
15 null) in step 42, but could at any time after its value is stored. Then, in step 44, control can be returned to a higher level process.

FIG. 5 is a flow chart of steps for carrying out illustrative process 50 of outputting one or more
20 result objects according to step 16 of FIG. 1.

In process 50, a graphical user interface for selecting, manipulating, and outputting result objects is provided. In step 52, a user can select and/or manipulate one or more previously created result
25 objects. Selection of result objects typically involves designating one or more preexisting result objects, but could involve designating result objects that are in the process of being created, such as according to process 40. Manipulation of result
30 objects could include any number of conventional graphical processes, including, for example, zooming, panning, resizing, etc. In step 54, a user can output one or more current result objects, which may be composite objects in accordance with this invention.
35 Outputting result objects can include storing them as files, displaying them on a display screen, and/or

printing them on any printing medium (e.g., paper).
FIG. 5 indicates that either of steps 52 and 54 can be
performed repeatedly, and in any combination, as
desired. At any time during process 50, a user may
5 elect to quit in step 55. It will be appreciated that
process 50 could be run according to this invention as
an entirely separate thread or process.

FIG. 6 is a flow chart of steps for carrying
out an illustrative embodiment of process 50 according
10 to this invention. Although any number of result
objects can be created and displayed according to this
invention, three composite result objects, which were
created according to this invention, are described in
detail below. The three result objects include a map
15 chart, which can be displayed in step 61, a jitter
chart, which can be displayed in step 62, and a
histogram chart, which can be displayed in step 63. As
explained more fully below, FIG. 8, for example, shows
user selectable buttons 101, 102, and 103, which are
20 labeled "Map/Trace," "Histogram," and "Jitter,"
respectively, for displaying respective charts in
steps 61-63. Each of these result objects were
designed to capture different aspects of data retrieved
in step 13 of FIG. 1. It will be appreciated that
25 other result objects can be designed to capture other
aspects of the data, including, for example image
chart 240, as shown in FIG. 35.

A "map" chart is a result object that can be
used for graphically displaying operational and
30 nonoperational features as a function of position. In
one embodiment, the features are superimposed on a
schematic of an optical disc. Examples of operational
data features that have been used according to this
invention include track markers and data collection
35 start and stop markers. Examples of nonoperational
data features include data features that corresponds to

nonoperational structures, such as beads. It has been found that a map chart displayed in accordance with this invention is useful for finding spatially-dependent correlations between mapped features on nearby (e.g., adjacent) tracks and for finding other qualitative relationships between such data features.

For example, a map chart (and/or a "trace" chart, which is discussed more fully below) can be helpful in determining whether multiple amplitude variations on two or more adjacent tracks correspond to a single, underlying structure. This could occur, for example, when a single nonoperational structure, such as an analyte-specific signal element (e.g., a bead), is sufficiently large to produce amplitude variations (i.e., a cluster of amplitude variations) on two or more tracks. A "cluster profile" characterizes the spatial arrangement, magnitude, and/or shape of such amplitude variations. It has been discovered that different types of signal elements can produce different cluster profiles. Therefore, according to this invention, data that includes a cluster of amplitude variations can be compared, using any conventional comparison technique, with one or more known cluster profiles in order to identify the type of underlying structure. As mentioned above, map and/or trace charts can be used to visually identify clusters. FIG. 11b, for example, is a zoomed-in map chart 122a that shows seven clusters 198, each of which includes three or four distinct features (e.g., features 199a, 199b, and 199c).

As described briefly above with respect to distinguishing complex data features, an automated process can be used to identify unknown clusters appearing in the data. One example of such an automated process includes detecting and/or identifying a first data feature (e.g., according to process 40)

using a first set of criteria (e.g., amplitude and width criteria), and then detecting and/or identifying a second "local" feature using a second set of criteria. If a known cluster profile includes three or
5 more features, the automated process for identifying such a cluster can include additional detection steps. Once again, these data features correspond to physical structures and that the term local could be either refer to the real physical position of the underlying
10 structure of the mapped physical representation of the data feature.

As used herein, a local feature is one that is in close physical proximity to another feature. Close physical proximity can be defined using any
15 convenient selection rule. For example, a structure may be considered local if it is found in a physical region defined with respect to the position of the first structure. A local physical region could be a substantially two-dimensional physical surface or a
20 three-dimensional volume of physical space. Alternatively, a structure may be local if the mapped feature is within, or located at, a specified radial or tangential distance from the first structure (i.e., mapped feature) or located at a specified angular
25 orientation with respect to the track or plane of the first structure (i.e., mapped feature). For example, local features might be only those mapped features located in the radial plane at 0° and 180° measured from the track of the first mapped feature. Then, only
30 features on the first track would be considered local. Alternatively, local features may be only those located in the radial plane between 0° and 180° from this track. Then, only structures located on one side of the track in the radial plane would be considered local.

35 It will be appreciated that a cluster of data features could appear in the data when two or more

discontinuous data features (e.g., patterns) correspond to different structures (e.g., different physical portions of a single bead, multiple coupled beads, etc.) positioned about 360° apart (e.g., on adjacent turns) of a spiral track. It will be further appreciated that any useful selection rules could be used to identify such clusters and that the "local" definitions described above are merely demonstrative. It will be further appreciated that two or more of these selection rules could be used in combination, as necessary.

A "histogram" chart is an example of a result object that can be used for graphically displaying (i.e., in a histogram) information regarding nonoperational structures. In particular, it has been found that a histogram chart displayed in accordance with this invention (such as the one shown in FIG. 12) can be useful for determining appropriate amplitude thresholds, such as for use in process 40 of FIG. 4.

For example, FIG. 12 shows a histogram chart in which each segment (i.e., bin) along the X-axis corresponds to a range of amplitudes for all data points. FIG. 12, then, shows that the majority of the sample data points is just above -0.6 volts. This helps to determine the threshold that can be used to separate random noise from the features of interest. The goal, then, could be to set the threshold as low as possible without processing an inordinate amount of data points. Thus, if the threshold were set to only count features below -0.6 volts, then, according to FIG. 12, the majority of the data would not be processed.

A "jitter" chart is another example of a result object that can be created and output according to this invention. A jitter chart may be used for graphically displaying (e.g., in a histogram) jitter.

Jitter normally refers to any rapid variation in the amplitude, frequency, or other characteristic of a signal, including, for example, variation in the width of data features. Process 40 of FIG. 4 shows one way
5 to detect data features and to determine widths for a given data set.

FIG. 13 shows jitter chart 123, in which each segment (i.e., bin) along the X-axis corresponds to a range of detected feature widths. It has been found
10 that display of a jitter chart in step 62 can be useful for determining minimum and maximum acceptable widths. For example, FIG. 13 shows a collection of features between about 3.4 μm and about 4.6 μm . If the same range is chosen by setting the minimum and maximum
15 acceptable widths to 3.4 and 4.6 μm , substantially the entire collection could be accurately counted.

Returning to FIG. 6, a user is provided with an ability to modify and output result objects, which may already be displayed, in steps 64 and 65. These
20 steps have already been described to some degree with reference to steps 52 and 53, so their description here is abbreviated. Modifying in step 64 can include, for example, selecting, zooming, and panning result objects. In a preferred embodiment, a user can
25 manipulate global aspects of the result objects. Zoom level and pan position are examples of global aspects because they can be used with more than one result object. In step 65, one or more result objects (or components thereof) can be output as desired.

FIG. 7 is a flow chart of steps for carrying
30 out process 70, which is an illustrative embodiment for outputting a map chart (and an optional trace chart) according to step 16 of FIG. 1, step 54 of FIG. 5, or step 61 of FIG. 6 of this invention.

35 In step 71, a user is provided with a number of control options associated with a trace chart, such

as trace chart 172 of FIG. 20. Although these options are only for use with a trace chart in the example shown, these options can also be used with any other result object, if desired. A trace chart displays raw or processed data. For example, as shown in FIG. 20, trace chart 172 displays the raw data that underlies certain features shown in map chart 171.

Trace options can be provided to a user in step 71. As shown in FIG. 8 (best in FIG. 8c), these options may be provided to a user in trace region 180 when trace tab 181 is selected, or, alternatively, be permanently available (not shown). It will be appreciated that the exact positions of trace region 180 and trace options 182-189 are merely illustrative.

Located at the top of trace region 180 is "Track Frst/Nbr," which identifies first trace track 182 and trace number 183. As shown in FIG. 20, track 182 is the first trace displayed in trace chart 172. Trace number 183 is the number of tracks displayed in trace chart 172. Together, first track 182 and trace number 183 define the range of traces (i.e., tracks) included in trace chart 172. This range may be useful because it can include substantially fewer tracks than are shown in map chart 171. By choosing an appropriate range, a user can display a convenient subset of tracks for detailed analysis of raw or processed data. In one embodiment, the tracks included in the trace chart can be highlighted, or otherwise identified, in the map chart.

"Multi-Trace Offset (in Volts)" identifies offset 184 and is located in trace region 180. Offset 184 contains a value in volts that determines the vertical distance between successive traces of trace chart 172. Without an offset, all of the traces would be superimposed on top of one another. "Merge

Panes" identifies merge button 185. When selected, merge button 185 eliminates space 175 between map chart 171 and trace chart 172, causing the two charts to merge (not shown). This allows more resolution and space for displaying map and trace charts by eliminating "dead" space between the two charts.

"Print with Map" identifies print button 186. When button 186 is selected, trace chart will automatically print when a map chart prints. "Select to Zoom" identifies zoom button 187. When selected, a user is provided with an opportunity to select with a pointing device (e.g., a mouse) a region (i.e., subset) of map chart for display in a trace chart without specifying the first trace track and number of traces. "Hide" and "Show" identifies Hide and Show Trace buttons 188 and 189. When a map chart is being displayed in accordance with this invention, "Show" button 188 provides a user with an ability to simultaneously display a trace chart. Alternatively, "Hide" button 189 provides a user with an ability to not display a trace chart. In FIG. 20, for example, map chart 171 is displayed simultaneously with trace chart 172. In FIG. 19, map chart 129 is displayed without a trace chart. Although a trace chart can be linked to a map chart in one illustrative embodiment of this invention, it will be appreciated that the trace chart and the map chart need not be linked and could be displayed separately.

In step 72, a user is provided with a number of zoom and pan control options for displaying result objects according to this invention. As shown throughout FIGS. 8-20, these options may be used with any type of result object, including map and trace charts, histogram charts, and jitter charts. The location and functions of these zoom and pan control options are shown and described below.

In step 73, visual options are provided to a user. These options can be made provided in a visual control, such as panel 190, when visual tab 191 is selected (FIG. 11). It will be appreciated, however, that a graphical user interface according to this invention could provide visual control options to a user at any time, if no such tab were used. When a current result object is a composite one, visual control panel 190 may allow a user to select one or more component result objects (e.g., viewable classes) for individual or combined display.

Rather than display data, a map chart replaces raw or processed data (e.g., that correspond to particular nonoperational structures) with mapping markers. A mapping marker is used to identify any discernible feature in the data, including, for example, a single data item, a group of data items, or a cluster of features. Mapping markers of any type can be used according to this invention, including the solid squares shown in FIG. 11. Preferably, the type of markers displayed is user-selectable. Some of the different types of markers that may be selected and displayed on a map chart include, but are not limited to, solid and open squares (e.g., "■" and "□"), solid and open diamonds (e.g., "◆" and "◇"), solid and open circles (e.g., "●" and "○"), up and down carets (e.g., "^" and "v"), etc. Furthermore, markers of different types, sizes, and colors can be displayed simultaneously on a single map chart to identify and differentiate between different types of data features. "Mapping Markers" identifies marker type 192 in visual panel 190. In FIGS. 10, 11, 14-20, "Solid Square1" is the selected type of mapping marker, and is used for display in their respective map charts.

Features can be grouped into viewable classes for inclusion in result objects and output, such as in

map charts. An example of a viewable class is the set of features that meets specific selection rules (e.g., width criteria). Map charts can then display the selected viewable class by replacing the data

5 corresponding to selected features with viewable elements. Any type of viewable element can be displayed in map charts in accordance with this invention, including, for example, circles, lines, spheres, ellipses, etc. Preferably, the type of

10 viewable classes displayed is user-selectable. Some of the different types of viewable classes that may be selected (e.g., as shown in FIGS. 10, 11, 14-20) and displayed in a map chart include, but are not limited to, "MapBounds," "MapCircle," "MapTrack,"

15 "MapTracedTrack," "MapPoint," "MapSphereEllipse," "MapSphereCircle," "MapSphereLine," "MapObjectLine," "TraceLine," "TraceThreshold," etc. Each viewable class can be defined differently and, when used to create a map chart, can provide a user a unique

20 different way to view the data. As shown in the FIGS., the ability to select a particular viewable class can be provided on visual panel 190 as viewable class 193 and is identified by "Viewable Classes." "Color" button 194, when selected, provides the user to select

25 one or more colors.

Rather than displaying viewable classes on a map chart, another embodiment according to this invention displays raw or processed data on a map chart. In this case, data are not replaced with

30 viewable elements. Rather, raw or processed data are superimposed on a representation of an optical disc, which allows a user to analyze representations of mapped data. Such analysis can be facilitated with one or more image processing features (e.g., smoothing,

35 amplification, etc.).

As shown in FIG. 14b, printing options are provided to a user in step 74 with "Print" and "Print SetUp" buttons, possibly on printer panel 200 when printing tab 201 is selected. Alternatively, printing options can be provided to a user on a drop down menu.

After any of steps 72, 73, and 74, a map chart may be displayed in step 76, with or without a trace chart in step 77, in accordance with the particular display options selected (e.g., whether "Hide" button 188 or "Show" button 189 is engaged). After selected result objects are displayed in steps 76 and 77, a user can repeat the process by immediately returning to the beginning of process 70 or by printing the map and/or trace chart(s) in step 79a directly. In step 79, a user may select to exit process 70.

Alternatively, a user may be provided an opportunity to create a submap file in step 75, such as by modifying a current map chart and then saving the modified object. This opportunity could be made available to a user when the user selects "file" and then "Save" (see below). In one embodiment, the user is provided with an ability to specify a submap filename and header information, and to process map data and trace information.

Illustrative embodiments of graphical user interfaces according to the present invention, showing various features and options, are shown in FIGS. 8-20. Because many of the features of this invention have already been described in some detail above, the description of the graphical user interface that follows is somewhat abbreviated.

FIG. 8 shows an illustrative embodiment of initial graphical user interface screen 100 according to this invention.

Region 110 of screen 100 includes a number of Windows™-based options, including "File," "View,"

"SubMap," and "Help." When selected, these options provide a user with a drop-down menu that includes additional details or options.

When "File" is selected, a drop-down menu may
5 be provided to a user. Such a drop-down menu can contain various file-related options, including "Open," "Save," "Print," and "Print Setup." An "Open" option can be one way to initiate data retrieval according to step 13 of FIG. 1. "Save" and "Print" options can be
10 used to initiate data analysis and output in steps 14 and 16 of FIG. 1. A standard option that may be further included in such a drop down menu, even though unrelated to file activities, is the self-explanatory "Exit" button.

15 When "View" is selected, a drop-down menu can be provided to a user. Such a drop-down menu can contain various result object viewing options, including "Map," "Trace," "Histogram," "Jitter," and "Debug Information." When "Map," "Trace," "Histogram,"
20 or "Jitter" is selected, the respective chart(s) may be displayed in charting region 120. As explained above, another way to display these charts is through user selectable buttons 101, 102, and 103. When "Debug" is selected, a debug information panel, such as panel 170
25 of FIG. 9, may be provided. Some of the information that can be included in panel 170 is current track being processed and number of data points processed (i.e., "Trk Curr/NbrPts") 171a and 171b, number of features detected and number of these features that
30 meet the width criteria, i.e., identified as spheres ("Nbr Pts/Sphs") 172a and 172b, total number of data points read from the file ("Total Pts Read") 173, current position of the data file in bytes ("File Position") 174, starting and ending points plotted in
35 the chart ("Points Plotted") 175a and 175b, number of skipped points passed and failed ("Points

Skipped") 176a and 176b, high and low numbers of points per track ("Points Per Trk") 177a and 177b, total number of data points tested during processing ("Total Pts Tested") 178, and difference between the number of
5 detected features and number of those features determined to correspond to spheres ("Difference") 179.

When "Submap" is selected, a drop-down menu may also be provided to a user that contain one or more options relating to a subset of the map chart,
10 including "Save" and "Restore." The "Save" option can be one way to initiate data storage according to steps 75 and 78 of FIG. 7. The "Restore" option can be used to retrieve previously stored data or result objects, such as according to step 13 of FIG. 1.

15 In FIG. 8, no data are displayed in map chart 121. In this embodiment, and as explained in more detail above, a map chart can be used to map result objects (e.g., that may include operational and/or nonoperational data) onto optical
20 representation 130. For this purpose, the concentric circles superimposed on chart 110 depict various physical and/or logical boundaries of disc 130. For example, innermost circle 132 may depict the outermost circumference of the mounting ring of disc 130, with
25 circle 135 depicting the outer diameter of optical disc 130. Circle 133 may depict the stacking ring or, alternatively, may depict the innermost edge of data storage region 131, commonly referred to as the "lead-in" boundary. Similarly, circle 134 will often depict
30 the outermost edge of data storage region 131 and is, in such cases, sometimes referred to as the "lead-out" boundary. The x and y axes of chart 120 are measured in distance (i.e., μm) from the center of optical disc 120.

35 Turning now to process control panel 140 (shown best in FIG. 8a), it can be seen that a user can

specify various program parameters for processing data according to one or more decoding processes (e.g., process 40 of FIG. 4). After specifying appropriate program parameters, data can be analyzed and result
5 objects can be created (i.e., step 14 of FIG. 1). In an alternative embodiment, data analysis can be performed using one or more default or predetermined program parameters. The program parameters shown in panel 140 are now described.

10 "Trk Start/Stop" identifies start and stop data track fields 141 and 142 used in a decoding process according to this invention. Together, fields 141 and 142 define a range of tracks. As shown in FIG. 8, the default values of these track fields
15 are 800 and 830. After data 160 is loaded, a map chart can be displayed, as shown in FIG. 10. The start and stop tracks used in FIG. 10 are 1 and 2,000. It will be appreciated that although a user may choose to zoom in on data 160 of map chart 120 with zoom window 152,
20 as shown in FIG. 11 (where only a subset of tracks is displayed), the start and stop tracks specified in fields 141 and 142, respectively, remain unchanged. Alternatively, the start and stop tracks displayed in fields 141 and 142 could reflect the dimensions of the
25 zoom window.

"TH Raw/Volts" identifies amplitude threshold fields 143 and 144. Field 143 contains a digital representation of the amplitude threshold between 1 and 4096. It will be appreciated that the maximum
30 value depends on the level of quantization performed by the analog-to-digital converter used to convert the time-varying signal. The value in field 144 is an equivalent voltage corresponding to the value in field 143. As explained above, other threshold
35 criteria could be used, including the sign and/or slope of the time-varying signal.

"Sph Min/Max" identifies minimum and maximum acceptable widths 145 and 146. As already described with respect to step 47 of FIG. 4, a width can be calculated for a feature (such as a bump or a dip) in a time-varying signal. The width corresponds to the size (in units of time or distance) of the underlying structure and scales with the number of data items (e.g., points) that meet the amplitude threshold criteria. If the measured width falls within the range defined by fields 145 and 146 (e.g., see step 50 of FIG. 4), a result object corresponding to the feature can be stored for output. Together, the minimum and maximum acceptable widths defines a range (i.e., a window) of acceptable widths.

Three user-selectable buttons are provided in panel 140. "Start" button 147 and "Stop" button 148 starts and stops data analysis (e.g., processing according to process 40 of FIG. 4). "Clip" button 149 provides a user with another opportunity to save a modified map chart (e.g., creating a Submap according to steps 75 and 78). Once again, the user can be provided with an ability to specify a Submap filename and/or header information, and to further process map data and/or trace information.

Near the bottom of panel 140 are a few display-related information boxes. "Trk Upd/Curr" identifies both the number 149a of tracks to be processed between display updates and the number 149b of the current track being processed. "Nbr Pts/Sphs" identifies the number 149c of data points processed and the number 149d of data features that meet the width criteria -- namely, the number of features that fall within the range defined by minimum and maximum acceptable widths 145 and 146.

Control panel 150 (shown best in FIG. 8b) includes various zoom and pan control options.

Although control panel 150 is shown on the right hand side of the interface, it will be appreciated that panel 150 can be located at any convenient position. Zooming may be controlled with a pointing device (e.g., a mouse), zoom arrows 151, and/or zoom edit box 153. Similarly, panning may be controlled with a pointing device (e.g., a mouse), pan arrows 154, and/or pan edit box 155.

Control panel 150 includes three options that are used exclusively for controlling zoom. First, "Zoom Off" identifies Zoom Off button 156. When selected, button 156 prevents a pointing device from controlling the zoom control. Second, "Zoom In" identifies Zoom In button 157. When selected, button 157 allows a pointing device to be used for selecting a window (i.e., box) in a currently displayed result object (e.g., a map chart). After being selected, the current result object (e.g., map chart) is redisplayed with the portion defined by the box enlarged. Third, "In/Out" identifies In/Out button 158. The purpose of In/Out button 158 is essentially the same as Zoom In, except for one difference. If a zoom box (e.g., box 152) is drawn from lower right hand corner 152a to upper left hand corner 152b, the zoom power will be adjusted in proportion to the area of the box compared to the area of the current chart.

Control panel 150 also includes one option that is used exclusively for controlling the pan direction. "Pan" identifies pan button 159, which, when selected, allows a map chart to be panned by a user.

Finally, control panel 150 includes two options that can affect both the zoom and pan settings. First, "Reset" identifies reset button 159a, which, when selected, resets a map chart to a default display

size and position. Second, "Recall" identifies recall representation 159b, which identifies which of the previously used zoom (and/or pan) displays is currently being viewed.

5 FIG. 12 shows an illustrative embodiment of a graphical user interface with histogram chart 122b constructed according to this invention. A histogram chart shows occurrences of various events as a function of some variable and usually includes a number of
10 vertical (or horizontal) rectangles of varying lengths. Histogram chart 122b shows the number of data points in various segments of the signal amplitude (e.g., volts) band. Thus, the x-axis of chart 122b represents the band of possible signal amplitudes of data points
15 detected during a decoding process (e.g., process 40 of FIG. 4). The y-axis represents the number of data points detected within a segment (i.e., bin) of the amplitude band. As shown in FIG. 12, chart 122b has a substantial peak at about -0.2 Volts.

20 FIG. 13 shows an illustrative embodiment of a graphical user interface with jitter (e.g., width) histogram chart 123 constructed according to this invention. Although jitter chart 123 is a histogram, the term "jitter" is used to distinguish it from
25 amplitude histogram chart 122b. Jitter chart 123 shows the number of data points in various segments of a width band. Thus, the x-axis has units of distance (e.g., μm) or time and represents the width of a data feature detected during a decoding process (e.g.,
30 process 40 of FIG. 4). The y-axis represents the number of features that fall within a particular width segment. As shown in FIG. 13, chart 123 includes a plurality of distinct peaks, including peaks at about 1.8, 3.8, and 4.4 μm .

35 It has been discovered that the region around the 1.8 μm peak likely corresponds to dust and other

undesirable particles on or within the optical disc. It has also been discovered that the peak that extends from 3.8 μm to 4.4 μm correspond to analyte-specific signal elements (i.e., paramagnetic beads) that are
5 known to have diameters of about 2.8 μm . Jitter chart 123, then, can be used to set the minimum and maximum acceptable widths 145 and 146. Specifically, by setting the minimum and maximum acceptable widths to 3.5 μm and 4.3 μm , nearly all the data features that
10 correspond to the beads can be accurately sorted, such as for counting.

It will be appreciated that amplitude threshold 143 (i.e., used by process 40) will affect calculated feature widths and, thus, will affect
15 sorting and counting accuracy. Thus, minimum and maximum acceptable widths should be adjusted accordingly. For example, if amplitude threshold 143 were to be decreased, widths measured by process 40 would correspondingly increase. This increase is
20 reflected by a rightward shift of the peaks in jitter chart. Then, in order to ensure that the proper range of acceptable widths is used, the minimum and maximum acceptable widths 145 and 146 should be increased accordingly. Therefore, it will be appreciated that
25 the best choice of values for amplitude threshold 143, and minimum and maximum acceptable widths 145 and 146, are interdependent.

Based on this interdependent relationship, an automated method of selecting a amplitude threshold is
30 provided. In a first step, data is provided. In a second step, an amplitude threshold estimate is selected and used in a decoding process, such as the one shown in FIG. 4. A result object is thereby generated that includes the width of each detected
35 feature in the data. In the next step, these widths are analyzed by segregated them into a series of width

segments (which could be used to render a histogram chart). Next, the maximum number of features in a single segment (or a group of adjacent segments) is stored along with the amplitude threshold used by the
5 decoding processes to calculate the widths. The process can then be repeated with varying thresholds until the optimal threshold is selected that produces the largest maximum number of features that fall within the single segment or group of adjacent segments.

10 It will be appreciated that this process could be used for detecting multiple optimal thresholds. For example, when an optical disc includes two or more types of nonoperational structures, each corresponding feature may have different optimal
15 thresholds. In this case, different optimal thresholds can be selected by repeating the above-described process for each maximum (i.e., largest number of features) in the histogram that corresponds to a different nonoperational structure.

20 An automated method of counting nonoperational features is also provided, and can be used after a amplitude threshold has been selected according to the method described above. Based on the statistical distribution of segregated widths described
25 above, a method of counting the nonoperational features includes (1) calculating a standard deviation σ of the distribution of widths about a peak (e.g., the segment or segments with the maximum number of features), and then adding the number of features that fall within a
30 certain number of those standard deviations. For example, if it is determined that the maximum number of features fall in a bin (i.e., segment) centered at $2.8 \mu\text{m}$, and that σ is $0.5 \mu\text{m}$, then the number of features that fall within $2.8 \pm 0.5n \mu\text{m}$, where n is an integer,
35 could be easily calculated by adding the features that fall within the segments defined by that range.

Although the value of n can be any integer, the value is preferably between 1 and 5, and a value of 3 has been successfully used.

It will be appreciated that this counting
5 process could be used for counting two or more types of features in a single data set by repeating the process for secondary maxima (i.e., largest numbers of features). For example, when an optical disc includes two or more types of nonoperational structures, each
10 type of nonoperational structure could correspond to peaks centered about different widths (e.g., 2 μm and 5 μm). Because each peak will normally have different statistical distributions, a different standard deviations can be calculated and used for each count.

15 FIG. 14a shows an illustrative embodiment of a graphical user interface, including map chart 124, that has been constructed according to this invention. As indicated by control panel 150, map chart 124 only shows a zoomed-in area. Specifically, map chart 124
20 shows the tracks located in the region between about 24,575 and about 24,620 μm of the y-axis and between about -842 and -894 μm of the x-axis. Two different types of objects are included in map chart 124: horizontal lines and ellipses. The ellipses
25 of map chart 124 represent detected features that meet the width criteria defined by the minimum and maximum acceptable widths 145 and 146 (i.e., greater than 2.7 μm and less than 4.1 μm). The size (e.g., horizontal distance) of the ellipses correspond to the magnitudes
30 of the underlying structures. The horizontal lines of map chart 124 represent the width of detected features that do not meet the width criteria. Thus, data features that have widths less than 2.7 μm and greater than 4.1 μm appear as horizontal lines.

35 FIG. 15 shows an illustrative embodiment of a graphical user interface, including map chart 125, that

has been constructed according to this invention. Like map chart 124, map chart 125 only shows the tracks located in the region between about 24,575 and 24,620 μm of the y-axis and between about -842 and -894 μm of the x-axis. Only solid square mapping markers are shown in FIG. 15. There can be no visible viewable objects shown because viewable classes "visible" button 195 is not selected. The mapping markers shown in FIG. 15 correspond to all of the data features found within the zoomed region, regardless of their widths.

FIG. 16 shows an illustrative embodiment of a graphical user interface, including map chart 126, that has been constructed according to this invention. Like map charts 124 and 125, map chart 126 only shows the tracks located in the region between about 24,575 and 24,620 μm of the y-axis and between about -842 and -894 μm of the x-axis. Unlike map chart 125, which includes solid square mapping markers, map chart 126 includes no mapping markers. Rather, map 126 includes one viewable class -- spheres. The spheres were created using minimum and maximum acceptable widths of 2.7 μm and 4.1 μm , respectively.

It will be appreciated that a map chart created according to this invention can include any number of viewable classes with different width criteria for detecting different size or type signal elements. For example, FIG. 17 shows an illustrative embodiment of a graphical user interface, including map chart 127, that has been constructed according to this invention. Like map charts 124-126, map chart 127 only shows the tracks located in the region between about 24,575 and 24,620 μm of the y-axis and between about -842 and -894 μm of the x-axis. Unlike map chart 126, which includes a viewable class of spheres, map chart 127 includes a different viewable class -- ellipses. The spheres and ellipses included in map

charts 126 and 127 were created with different processes using different width criteria. In particular, the spheres were created using minimum and maximum acceptable widths of 2.7 and 4.1 μm ,

5 respectively, and the ellipses were created for any features that met the threshold criteria (i.e., crossed the threshold). The width of each ellipse represents the length of time the data met the criteria (see FIG. 4).

10 FIGS. 18 and 19 show illustrative embodiments of a graphical user interface, including map charts 128 and 129, respectively, that have been constructed according to this invention. Like map charts 124-127, map charts 128 and 129 only show tracks located in the
15 region located between about 24,575 and 24,620 μm along the y-axis and between about -842 and -894 μm along the x-axis. Like map chart 127, map chart 128 only shows features that have widths that fall between the minimum and maximum acceptable widths of 2.7 and 4.1 μm ,
20 respectively. The only difference between map chart 127 and map chart 128 is that map chart 128 uses one viewable class of horizontal lines -- not two viewable classes of spheres and ellipses. Furthermore, map chart 129 only shows features that have widths that
25 fall outside the range defined by the minimum and maximum acceptable widths of 2.7 and 4.1 μm , respectively. The same features were also shown in FIG. 124, but in combination with features (i.e., two viewable classes of spheres and ellipses) that fall
30 inside the same range. The physical widths used by this process were calculated by dividing by 10 the values used in minimum and maximum acceptable widths 145 and 146.

FIG. 20 shows an illustrative embodiment of a
35 graphical user interface, including map chart 171 and trace chart 172, that has been constructed according to

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remained adherent to the dried disc presumably through noncovalent interactions with the disc's metallic surface.

FIG. 21 shows a two-dimensional composite
5 light microscopic picture of the laser proximal surface of the disc. The lighter areas in the center of each individual field are reflection artifacts of the microscopic illumination. The adherent spheres can be seen aligned substantially in the radial direction.

10 FIG. 22 is a higher magnification light microscopic picture showing a portion of the same disc as shown in FIG. 21. The disc's continuous wobbled groove may be seen at this magnification as a series of essentially parallel tracks, with the groove's radial
15 direction disposed horizontally in the light microscopic image and the disc's tangential direction being disposed vertically. The spheres are seen collectively to extend over the entire radial extent of the light microscopic field, and to overlies a number of
20 separate tracks.

A polycarbonate disc cover, manufactured essentially as described in copending and commonly owned U.S. Patent Application No. 09/311,329 filed May 14, 1999, incorporated herein by reference in its
25 entirety, was then attached over the disc's metal surface using several drops of methylethylketone applied to the disc's clamping ring, followed by mild pressure.

The disc with attached cover was then read
30 using a Ricoh 6200S CD-RW optical disc drive, with the drive's nonequalized HF output tapped, filtered, buffered, and discontinuously sampled using an ULTRAD-1280 dual 40 MHZ 12 bit A/D PCI data acquisition board (Ultraview Corporation, Orinda, CA). The digital
35 data were written to a file on computer hard disk. The

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digital data were thereafter input into a software program according to the present invention.

FIG. 23 shows a trace chart generated by the software, displaying the electrical response reported in the buffered HF signal during reading along a single one of the tracks that passes through the area of the disc shown in FIG. 22. Several deviations from baseline, representing discrete data features, are readily visible to visual inspection.

Three data features are approximately equal in width, shape, and maximum amplitude; the left-most one is smaller.

With respect to the three similar data features, the maximum width of 5 μm agrees with the size expected by combining the known diameter of the beads with the expected diameter of the laser beam at the center of the bead of the disc's metal surface. The biphasic shape is consistent with expectations of changes in reflectivity as the laser traverses (climbs) the leading edge of the spherical bead, traverses its center, and then traverses (descends) the lagging edge.

FIG. 24 shows a trace chart aligning, in X axis (i.e., radial) registration, the electrical responses reported in the buffered HF signal along four of the tracks that pass through the area of the disc shown in FIG. 22, with the track shown in FIG. 23 appearing as the second track from the top. FIG. 25 shows a trace chart aligning, in X axis (i.e., radial) registration, the electrical responses reported in the buffered HF signal along six of the tracks that pass through the area of the disc shown in FIG. 22. FIG. 26 shows a trace chart aligning, in X axis registration, electrical responses reported in the buffered HF signal along ten of the tracks that pass through the area of the disc shown in FIG. 22.

The radial alignment of the traces in FIG. 26 allows visual identification of data features clustered in the tangential direction. The uniphasic, low amplitude, data feature shown in FIG. 23 is now

5 suggested by the aligned traces of FIG. 26 to represent the edge of a nonoperational structure, the center of which produces higher amplitude, biphasic signals in adjacent traces.

FIG. 27 shows a map chart generated from the
10 same data. Ellipses mark the location of data features that meet the amplitude and/or width criteria set in the software for identification of beads; dots mark the location of data features that fail the amplitude and/or width criteria for beads. Comparison of the map
15 chart in FIG. 27 with the microscope photograph presented in FIG. 22 validates the initial mapping criteria and allows further refinement.

FIGS. 28-31 show map charts of the same data at progressively lesser degrees of zoom than in
20 FIG. 27, with FIGS. 30 and 31 additionally superimposing the mapped features upon a schematic of an optical disc. Comparison of FIGS. 29 and 30 with the composite photograph of FIG. 21 demonstrates the ability of the methods and apparatus of the present
25 invention digitally to mimic optical microscopic inspection of the disc surface.

EXAMPLE 2

Discrimination and Classification of Nonoperational Feature Structures Using Data Feature Patterns

30 A single data layer inverted wobble groove optical disc was manufactured essentially as described in co-pending and commonly owned U.S. Patent Application No. 09/311,329 filed May 14, 1999, incorporated herein by reference in its entirety.

An aliquot of 4 μm diameter blue polystyrene beads (available from Spherotech, Inc., of Libertyville, IL), 6.8 μm diameter blue polystyrene beads (available from Spherotech), and silica beads
5 (available from Sigris Research, Inc., of Brea, CA) was mixed in water and spotted onto the metal surface of the disc. The disc was then air dried. FIG. 32a is a light microscope image of the disc surface, showing an aggregation of beads that includes two silica
10 beads 201, a single 4 μm blue polystyrene bead 202, and three 6.8 μm blue polystyrene beads 203.

A polycarbonate cover was affixed to the disc and the disc assembly read as described in Example 1. The stored digital data were thereafter input into a
15 software program according to the present invention.

FIG. 32b is a trace chart aligning, in X-axis (radial) registration, the electrical responses reported in the buffered HF signal along ten of the tracks that pass through the region of the disc shown
20 photographically in FIG. 32a. A signal 204 above baseline occurs in the location of one of the silica beads, and is readily identified in the electrical signal despite the abutment of neighboring beads.

The above-baseline signal 204 that is
25 generated by the silica beads has also been observed using acrylic beads. Without wishing to be bound by theory, it is presently believed that the silica and acrylic beads, which are at least partially transparent, act as lenses to further focus the
30 incident laser light during reading. Another possible cause for an increase in the signal is reflection of laser light from the top portion of the proximal surface of the bead. Acrylate beads, which are commercially available with more uniform size
35 distribution than silica beads, present certain advantages on that basis.

The trace chart of FIG. 32b demonstrates that structurally dissimilar nonoperational structures may be discriminated and classified according to differing patterns that they create in the digital data.

5 Accordingly, the trace chart demonstrates that nonoperational structures may be chosen and/or designed for their ability to generate data features that may be readily discriminated using the methods and apparatus of the present invention.

10 FIG. 33 shows an illustrative embodiment of another map chart displayed according to this invention. FIG. 34 shows trace chart 220 displaying a single electrical response 231 reported in the buffered HF signal during reading along a single one of the
15 wobble tracks that passes through the area of the disc shown in FIG. 33. Also shown on FIG. 34 is threshold 232, which was used in accordance with the decoding algorithms previously described. Each time signal 230 crosses threshold 232 in a downward
20 direction (signal 230 has a negative slope), a circular marker is placed at the crossing (e.g., marker 234). Above each marker, there a horizontal segment (e.g., segment 236) is added that can reflect the measured width of data feature that follows the crossing. As
25 seen in FIG. 34, because of the large number of crossings, each horizontal segment is horizontally and vertically offset from the original crossing.

Finally, FIG. 35 shows image chart 240 (i.e., a bit map image) that roughly corresponds to the wobble
30 tracks that pass through boxed area 222 of an optical disc schematic shown in FIG. 33. The black and white bit map image shown in FIG. 35 was created by assigning an intensity value to each bit of the image proportional to the amplitude of the signal response
35 (i.e., data) at that point. Thus, rather than mapping viewable objects (e.g., classes and markers) onto an

optical disc schematic, the magnitude of the signal can be represented directly by a displaying an assigned intensity.

5 All patents, patent publications, and other
published references mentioned herein are hereby
incorporated by reference in their entireties as if
each had been individually and specifically
incorporated by reference herein. While preferred
illustrative embodiments of the present invention are
10 described, it will be apparent to one skilled in the
art that various changes and modifications may be made
therein without departing from the invention, and it is
intended in the appended claims to cover all such
changes and modifications that fall within the true
15 spirit and scope of the invention.

What is claimed is:

1. A method for analyzing data acquired by reading an optical disc having at least one readable nonoperational structure, said method comprising identifying a pattern in said data that reports a physical property of said nonoperational structure.

2. The method of claim 1 wherein said data are a digitized sample of at least one analog signal.

3. The method of claim 2 wherein said at least one analog signal is derived from a signal selected from a group consisting of a high frequency signal, a tracking error signal, a focus error signal, and any combination thereof.

4. The method of claim 3 wherein said at least one analog signal comprises multiple analog signals.

5. The method of claim 4 further comprising:

combining said multiple analog signals
to form a combined analog signal; and
quantizing said combined analog signal
to form said data.

6. The method of claim 5 wherein said combining said analog signals comprises combining said analog signals in a synchronized manner.

7. The method of claim 2 further comprising:

quantizing each of said analog signals
to form individual digitized data sets; and

combining said individual digitized data sets to form said data.

8. The method of claim 7 wherein said combining said data sets comprises combining in a synchronized manner.

9. The method of claim 2 wherein said digital sample was acquired in a substantially continuous manner.

10. The method of claim 2 wherein said digital sample was acquired in a substantially noncontinuous manner.

11. The method of claim 1 wherein said pattern is substantially continuous within said digital sample.

12. The method of claim 11 wherein said substantially continuous pattern corresponds to a length along a track in a radial direction.

13. The method of claim 1 wherein said pattern is substantially discontinuous within said digital sample.

14. The method of claim 13 wherein said discontinuous pattern corresponds to a cluster of data features.

15. The method of claim 14 wherein at least two of said cluster data features correspond to different structures positioned along different turns of said disc.

16. The method of claim 13 wherein said discontinuous pattern includes multiple data features that correspond to at least one nonoperational structure.

17. The method of claim 13 wherein said discontinuous pattern comprises at least one discontinuity between two continuous regions, and wherein said discontinuity itself reports a physical property of said nonoperational structure.

18. The method of claim 17 wherein said discontinuity indicates that said continuous regions correspond to structures that are substantially tangentially located with respect to one another.

19. The method of claim 18 wherein said discontinuity indicates that said continuous regions correspond to structures on the same turn of a track.

20. The method of claim 17 wherein said discontinuity indicates that said continuous regions correspond to structures on different turns of said disc.

21. The method of claim 14 wherein said identifying comprises associating result objects that correspond to said data features.

22. The method of claim 14 wherein said reported physical property is a property disposed tangentially on said disc.

23. The method of claim 22 wherein said reported physical property is a structural size measured in a tangential direction.

24. The method of claim 1 wherein said reported physical property inheres in said nonoperational structure.

25. The method of claim 24 wherein said reported physical property is independent of an absolute position of said pattern in said data.

26. The method of claim 25 wherein said nonoperational structure produces a substantial analog signal in only one turn of a disc.

27. The method of claim 24 wherein said reported property depends upon a position of said pattern in said data.

28. The method of claim 27 wherein said at least one nonoperational structure produces a substantial analog signal in at least two different turns of a disc.

29. The method of claim 28 wherein said identifying comprises using the relative position of the pattern on the disc.

30. The method of claim 28 wherein said identifying comprises reporting the size of a bead that crosses at least two different turns.

31. The method of claim 1 wherein said identifying comprises identifying a plurality of nonoperational features, said method further comprising counting said plurality of nonoperational features.

32. The method of claim 1 wherein said physical property depends at least in part upon

disposition of said at least one nonoperational structure on said disc.

33. The method of claim 32 wherein said physical property depends on an optical interaction between a laser beam, at least one nonoperational structure, and the disc.

34. The method of claim 33 wherein said nonoperational structure is a translucent bead and said optical interaction is a lensing effect of said bead.

35. The method of claim 34 wherein said physical property is an ability of said bead to focus the laser beam near a groove of said disc.

36. The method of claim 32 wherein said reported physical property is independent of an absolute position of said pattern in said data.

37. The method of claim 32 wherein said reported physical property is dependent on a position of said pattern in said data.

38. The method of claim 1 wherein said trackable optical disc includes at least one spiral track.

39. A method of analyzing data generated by reading a trackable optical disc having a plurality of physically nonidentical concurrently readable nonoperational structures, said method comprising identifying patterns in said data that distinguish among said physically nonidentical nonoperational structures.

47. The method of claim 40 wherein said digital sample was acquired in a substantially continuous manner.

48. The method of claim 40 wherein said digital sample was acquired in a substantially noncontinuous manner.

49. The method of claim 39 wherein at least one of said patterns is continuous within said digital sample.

50. The method of claim 49 wherein said continuous pattern corresponds to a length along a track in a radial direction.

51. The method of claim 39 wherein at least one of said patterns is discontinuous within said digital sample.

52. The method of claim 51 wherein said discontinuous pattern corresponds to a cluster of data features.

53. The method of claim 52 wherein at least two of said cluster data features correspond to structures positioned along different turns of said disc.

54. The method of claim 51 wherein said discontinuous pattern includes multiple data features that correspond to at least one nonoperational structure.

55. The method of claim 39 wherein said identifying comprises identifying in a manner that is

independent of absolute position of said pattern in said data.

56. The method of claim 55 wherein said nonoperational structures produce discernable and substantial analog signals in only one turn of a track.

57. The method of claim 55 wherein said plurality of structures comprises at least two classes of structures, said method further comprising counting the number of at least one class of said structures.

58. The method of claim 55 wherein said identifying comprises identifying in a manner that is dependent of absolute position of said pattern in said data.

59. The method of claim 55 wherein said at least one class of nonoperational structure produces a substantial analog signal in two or more different turns of a track.

60. The method of claim 55 wherein said identifying comprises using relative positions of the patterns on the disc.

61. The method of claim 39 wherein at least one of said patterns depends at least in part upon disposition of said structures on said disc.

62. The method of claim 61 wherein said pattern depends on an optical interaction between a laser beam, at least one nonoperational structure, and the disc.

63. The method of claim 62 wherein said nonoperational structure is a translucent bead and said optical interaction is a lensing effect of said bead.

64. The method of claim 61 wherein said identifying comprises distinguishing patterns in said data in a manner that is independent of absolute positions of said patterns in said data.

65. The method of claim 61 wherein said identifying comprises distinguishing patterns in said data in a manner that is dependent on absolute positions of said patterns in said data.

66. The method of claim 39 further comprising counting at least one of said patterns in said data.

67. The method of claim 39, further comprising outputting a report that includes results of said identifying.

68. The method of claim 67 wherein said outputting comprises displaying said report visually.

69. The method of claim 68 wherein said displaying is on an electronic display.

70. The method of claim 67 wherein said outputting comprises printing said report on a tangible medium.

71. The method of claim 67 wherein said outputting comprises transmitting said report by sound.

72. The method of claim 67 wherein said outputting comprises transmitting said report remotely.

73. The method of claim 67 wherein said outputting comprises storing said report in a manner selected from a group comprising transient storing and permanent storing.

74. The method of claim 39 wherein said trackable optical disc includes at least one spiral track.

75. A method in a computer system of determining the relative physical locations of a first nonoperational structure and a second nonoperational structure on a surface of an optical disc, said method comprising:

reading said optical disc to generate data;

identifying in the data (i) a first pattern that reports a physical property of said first nonoperational structure and (ii) a second pattern that reports a physical property of said second nonoperational structure; and

calculating at least relative physical locations of said first and second nonoperational structures on the disc.

76. The method of claim 75 wherein said optical disc includes at least one start of record marker that is capable of triggering said reading, said reading comprising:

detecting said start of data marker; and
generating at least one data record in response to said detecting said marker.

77. The method of claim 76 further comprising:

detecting an end of data marker; and
terminating said reading in response to
said detecting said end of data marker.

78. The method of claim 77 wherein said detecting a start of data marker, said generating at least one data record, said detecting an end of data marker, and said terminating said generating is repeatedly performed, and wherein said data comprises data features between said generated data records.

79. The method of claim 75 wherein said reading occurs between a start of record marker and an end of data marker on said disc.

80. The method of claim 79 wherein said markers can be logical or physical markers.

81. The method of claim 75 wherein said calculating comprises calculating the locations by mapping the patterns in said data according to a predetermined mapping routine.

82. The method of claim 81 wherein said predetermined mapping routine uses a known position on said disc to mapping said patterns.

83. The method of claim 82 wherein said known position is selected from a group consisting of a start of record marker position and an end of marker position.

84. The method of claim 81 wherein said known position is selected from a group consisting of a

tangential position, a radial position, and a combination thereof.

85. The method of claim 75 wherein said first and second nonoperational structures are physically nonidentical, said identifying comprising distinguishing between and said first and second patterns.

86. The method of claim 75 wherein at least one of said identifying and calculating is performed iteratively to determine said relative physical locations.

87. The method of claim 75 wherein said surface is selected from a group consisting of an internal disc surface and an external disc surface.

88. The method of claim 75 wherein said trackable optical disc includes at least one spiral track.

89. A method in a computer system of mapping the physical locations of nonoperational structures on a surface of an optical disc, comprising:

determining a relative physical location of at least one of said nonoperational structures; and
marking an representation of the surface of an optical disc with at least one object that reflects said at least one relative physical location.

90. The method of claim 89 wherein said method of determining comprises:

reading said optical disc to generate data;

identifying in the data: (i) a first pattern that reports a physical property of said first nonoperational structure and (ii) a second pattern that reports a physical property of said second nonoperational structure; and

calculating relative physical locations of said first and second nonoperational structures on the disc.

91. The method of claim 89 wherein at least one of said nonoperational structures includes a plurality of distinguishable objects.

92. The method of claim 91 wherein each of said plurality of distinguishable objects corresponds to a separately identifiable pattern in said data.

93. A method in a computer system of classifying an object having at least one sub-centimeter dimension, said method comprising:

generating data by reading a trackable optical disc upon or within which said object is disposed as a concurrently readable nonoperational structure; and

identifying a pattern in said data that reproducibly distinguishes said object.

94. The method of claim 93 wherein said data are a digitized sample of at least one analog signal.

95. The method of claim 94 wherein said at least one analog signal is derived from a signal selected from a group consisting of a high frequency signal, a tracking error signal, a focus error signal, and any combination thereof.

96. The method of claim 95 wherein said at least one analog signal comprises multiple analog signals.

97. The method of claim 96 further comprising:

combining said multiple analog signals to form a combined analog signal; and

quantizing said combined analog signal to form said data.

98. The method of claim 97 wherein said combining said analog signals comprises combining in a synchronized manner.

99. The method of claim 96 further comprising:

quantizing each of said signals to form individual digitized data sets; and

combining said individual digitized data sets to form said data.

100. The method of claim 99 wherein said combining said data sets comprises combining in a synchronized manner.

101. The method of claim 94 wherein said digital sample was acquired in a substantially continuous manner.

102. The method of claim 94 wherein said digital sample was acquired in a substantially noncontinuous manner.

103. The method of claim 93 wherein said pattern is continuous within said digital sample.

104. The method of claim 103 wherein said continuous pattern corresponds to a length along a track in a radial direction.

105. The method of claim 93 wherein said pattern is discontinuous within said digital sample.

106. The method of claim 105 wherein said discontinuous pattern corresponds to a cluster of data features.

107. The method of claim 106 wherein at least two of said cluster data features correspond to one of either (a) different structures or (b) different portions of a single structure, that are positioned along different turns of said disc.

108. The method of claim 105 wherein said discontinuous pattern includes multiple data features that correspond to at least one nonoperational structure.

109. The method of claim 105 wherein said discontinuous pattern comprises at least one discontinuity between two continuous regions, and wherein said discontinuity itself reports a physical property of said nonoperational structure.

110. The method of claim 109 wherein said discontinuity indicates that said continuous regions correspond to structures on tracks that are substantially tangentially located with respect to one another.

111. The method of claim 110 wherein said discontinuity indicates that said continuous regions correspond to structures on a single turn.

112. The method of claim 110 wherein said identifying comprises associating result objects that correspond to said structures.

113. The method of claim 110 wherein said reported physical property is a property disposed tangentially on said disc.

114. The method of claim 113 wherein said reported physical property is a size measured in a tangential direction.

115. The method of claim 93 wherein said identifying comprises using the relative position of the pattern on the disc.

116. The method of claim 115 wherein said identifying comprises reporting the size of a bead that crosses at least two turns.

117. The method of claim 93 wherein said identifying comprises using a physical property that depends at least in part upon disposition of said at least one nonoperational structure on said disc.

118. The method of claim 117 wherein said physical property depends on an optical interaction between a laser beam, at least one nonoperational structural structure, and the disc.

119. The method of claim 118 wherein said nonoperational structure is a translucent bead and said optical interaction is a lensing effect of said bead.

120. The method of claim 119 wherein said physical property is an ability of said bead to focus the laser beam on a groove.

121. The method of claim 117 wherein said reported physical property is independent of a position of said pattern in said data.

122. The method of claim 117 wherein said reported physical property is dependent on a position of said pattern in said data.

123. The method of claim 93 further comprising counting at least one class of said patterns in said data.

124. The method of claim 93 wherein said identifying comprises comparing said identified pattern to at least one of a plurality of earlier-identified patterns.

125. The method of claim 93 further comprising outputting a report that includes a class of said object after said identifying.

126. The method of claim 125 wherein said outputting comprises displaying said report visually.

127. The method of claim 126 wherein said displaying is on an electronic display.

100	200	300	400	500	600	700	800	900	1000
100	200	300	400	500	600	700	800	900	1000

100	200	300	400	500	600	700	800	900	1000
100	200	300	400	500	600	700	800	900	1000

100	200	300	400	500	600	700	800	900	1000
100	200	300	400	500	600	700	800	900	1000

100	200	300	400	500	600	700	800	900	1000
100	200	300	400	500	600	700	800	900	1000

100	200	300	400	500	600	700	800	900	1000
100	200	300	400	500	600	700	800	900	1000

100	200	300	400	500	600	700	800	900	1000
100	200	300	400	500	600	700	800	900	1000

100	200	300	400	500	600	700	800	900	1000
100	200	300	400	500	600	700	800	900	1000

100	200	300	400	500	600	700	800	900	1000
100	200	300	400	500	600	700	800	900	1000

allocation parameter, a form parameter, and any combination thereof.

136. The method of claim 134 wherein said initializing comprises setting said at least one program parameter to a default value.

137. The method of claim 133 wherein said retrieving comprises retrieving said data from a source selected from a group consisting of a direct source and a stored data source.

138. The method of claim 137 wherein said retrieving comprises retrieving from a direct source, wherein said direct source provides a data stream.

139. The method of claim 137 wherein said retrieving comprises retrieving at least one data record from a stored data source.

140. The method of claim 139 wherein a data record comprises at least one data item.

141. The method of claim 140 wherein a data record comprises between 1 and about 30,000 data items.

142. The method of claim 139 wherein said at least one data record comprises at least two data records of differing sizes.

143. The method of claim 139 wherein said at least one data record comprises at least two data records of the same size.

144. The method of claim 137 wherein said source is predetermined.

145. The method of claim 137 wherein said source is determined by an external process.

146. The method of claim 137 wherein said source is determined by a user.

147. The method of claim 137 further comprising selecting a source, wherein said source is selected from a group consisting of a local data source and a remote data source.

148. The method of claim 137 wherein said data are selected from a group consisting of operational data, nonoperational data, and a combination thereof.

149. The method of claim 133 wherein at least one of said retrieving and said analyzing comprises filtering said data.

150. The method of claim 149 wherein said data corresponds to an amount of data, wherein said filtering comprises reducing said amount of data.

151. The method of claim 133 further comprising acquiring said data using an optical disc reader.

152. The method of claim 151 wherein said optical disc includes at least one start of record marker that is capable of triggering said acquiring, said acquiring comprising:

- detecting said start of data marker;
- generating at least one data record in response to said detecting said start of data marker.

153. The method of claim 152 wherein said acquiring further comprises:

detecting an end of data marker; and
terminating said acquiring in response to said detecting said end of data marker.

154. The method of claim 153 wherein said detecting a start of data marker, said generating data record, said detecting an end of data marker, and said terminating said generating are repeatedly performed, and wherein said data comprises data features between said generated data records.

155. The method of claim 154 wherein said acquiring occurs between a start of record marker and an end of data marker on said disc.

156. The method of claim 155 wherein said markers can be logical or physical markers.

157. The method of claim 133 further comprising filtering said data before said retrieving.

158. The method of claim 133 wherein said analyzing comprises processing one or more data records.

159. The method of claim 158 wherein said analyzing comprises distinguishing operational data features from nonoperational data features.

160. The method of claim 159 wherein said distinguishing yields at least one of said operational data features.

161. The method of claim 160 wherein said at least one of said operational data features corresponds to a structure that is selected from a group consisting of a tracking information structure, an address information structure, a disc speed indicating structure, and an end of data structure.

162. The method of claim 159 wherein said distinguishing comprises decoding at least one data record.

163. The method of claim 162 wherein said decoding comprises:

- identifying at least one of said nonoperational data features; and
- counting said nonoperational data features.

164. The method of claim 162 further comprising notifying at least one other process for further processing.

165. The method of claim 163 wherein said identifying comprises applying threshold criteria to said at least one data record.

166. The method of claim 165 wherein said applying comprises applying to said at least one data record at least one criterion selected from a group consisting of amplitude, sign, magnitude, slope, time period, width, and any combination thereof.

167. The method of claim 159 wherein said distinguishing comprises characterizing at least one data feature according to a method selected from a

group consisting of shape analysis, Fourier analysis, auto-correlation, masking, and any combination thereof.

168. The method of claim 167 wherein said characterizing comprises characterizing a cluster of data features in at least one data record.

169. The method of claim 133 wherein said generating comprises generating at least one chart selected from a group consisting of a map chart, a jitter chart, and a histogram chart.

170. The method of claim 169 wherein said generating comprises generating a map chart that includes at least one visible object selected from a group consisting of a mapping marker and a viewable class.

171. The method of claim 133 wherein said result object is selected from a group consisting of a simple result object that includes a single structure and a composite result object that includes a plurality of structures.

172. The method of claim 171 wherein said generating is selected from a group consisting of continuously generating during said retrieving and generating after said retrieving.

173. The method of claim 172 wherein said generating is upon detection of a feature in said data.

174. The method of claim 133 further comprising transmitting said objects to other processes.

175. The method of claim 133 further comprising providing a user an ability to select one of said result objects before said outputting.

176. The method of claim 133 wherein said providing comprises providing said user an ability to manipulate said result object before outputting.

177. The method of claim 176 wherein said ability to manipulate is selected from a group consisting of an ability to zoom, pan, and resize said result object.

178. The method of claim 133 wherein said outputting is selected from a group consisting of storing, displaying, and printing.

179. The method of claim 133 wherein any of said retrieving, analyzing, generating, and outputting can be performed iteratively.

180. The method of claim 133 wherein said generating comprises calculating debug information, and wherein said outputting comprises outputting said debug information.

181. The method of claim 133 wherein said trackable optical disc includes at least one spiral track.

182. A computer readable medium containing data acquired from an optical disc with a spiral track that includes concurrently readable nonoperational structures.

183. The medium of claim 182 wherein said data includes patterns that can be mapped according to positional information present in the digital data.

184. The medium of claim 183 wherein said data includes at least one result object that indicates the position of at least one of said nonoperational structures detected on a surface of said disc.

185. The medium of claim 184 wherein said surface of said disc is selected from a group consisting of an external surface and an internal surface.

186. A computer readable medium containing instructions for analyzing data from an optical disc with a spiral track that includes concurrently readable nonoperational structures.

187. A system for analyzing data acquired from a spiral trackable optical disc with concurrently readable nonoperational structures, said system comprising a computer capable of retrieving said data, analyzing said data, generating at least one result object, and outputting said at least one result object.

188. A system for remotely analyzing data, said system comprising:

a client computer capable of:

acquiring data from a trackable optical disc with concurrently readable nonoperational structures, and

transmitting said data over a remote connection; and

a server computer capable of:

receiving said data over the remote connection,

analyzing said data, and
generating at least one result object from said data.

189. The system of claim 188 wherein said remote connection is an Internet connection.

190. The system of claim 189 wherein said server computer is further capable of transmitting said at least one result object over the remote connection to the client computer.

191. The system of claim 189 wherein the trackable optical disc comprises at least one spiral track.

192. The system of claim 189 wherein said server computer is capable of analyzing by identifying patterns in said data that reproducibly distinguish underlying structures.

193. The system of claim 189 wherein said server computer is capable of analyzing by identifying a pattern in said data that reports a physical property of at least one of said nonoperational structures.

194. The system of claim 189 wherein said client computer is capable of acquiring data by reading a disc that has a plurality of physically nonidentical concurrently readable nonoperational structures, and wherein said server computer is capable of analyzing said data by identifying patterns in said data that distinguish among physically nonidentical nonoperational structures.

195. The system of claim 189 wherein said client computer is capable of reading the optical disc to generate data, and wherein said server computer is capable of:

analyzing the data by identifying in the data (i) a first pattern that reports a physical property of a first nonoperational structure and (ii) a second pattern that reports a physical property of a second nonoperational structure; and

calculating at least relative physical locations of said first and second nonoperational structures on the disc.

196. The system of claim 189 wherein said server computer is capable of analyzing by mapping physical locations of structural nonoperational structures on a surface of an optical disc by:

determining a relative physical location of at least one of said nonoperational structures; and

marking a representation of the surface of an optical disc with at least one object that reflects said at least one relative physical location.

197. The method of claim 188, wherein said disc is trackable and said nonoperational structure is concurrently readable with said disc's trackable attributes.

198. A computer readable medium containing instructions for analyzing data from an optical disc according to the method of claim 188.

199. A computer readable medium containing instructions for analyzing data from an optical disc according to the method of claim 197.

200. A visual display of at least one software-generated object, wherein said object reports a physical property of a nonoperational structure of an optical disc.

201. The display of claim 200, wherein said property is the position of said nonoperational structure on said disc.

202. The display of claim 200, wherein said property is the size, in at least one dimension, of said nonoperational structure.

203. The display of claim 202, wherein said dimension is in the disc's tangential direction.

204. The display of claim 200, wherein said display is ephemeral.

205. A method for automatically selecting an amplitude threshold for use in counting nonoperational structures in data acquired by reading an optical disc having at least one readable nonoperational structure, said method comprising:

processing a number of different estimated amplitude thresholds, said method comprising processing each of said different estimated amplitude thresholds by:

selecting an estimated amplitude threshold,

decoding said data using said estimated threshold to generate a result object, said result object at least comprising widths of decoded nonoperational features,

segregating said widths into a series of width segments, and

selecting an optimal threshold from said different estimated thresholds, wherein said optimal threshold is the estimated threshold that causes said decoding to produce a largest of said maximum number of features that fall within its peak segment.

segregating detected widths into a series of width segments, thereby creating a statistical distribution of widths that includes at least one peak;

calculating a standard deviation of said
distribution of widths about said at least one peak;
and

adding the number of features that fall within a certain number of said standard deviations.

METHODS AND APPARATUS FOR ANALYZING
OPERATIONAL AND NONOPERATIONAL DATA
ACQUIRED FROM OPTICAL DISCS

Abstract

5 Methods and apparatus for analyzing
nonoperational data acquired from optical discs, and in
particular, trackable optical discs having concurrently
readable nonoperational structures are provided.
Analysis can involve identifying patterns in the data
10 that reproducibly distinguish underlying structures, or
identifying patterns in the data that report physical
properties of the nonoperational structures. When an
optical disc has a plurality of physically nonidentical
concurrently readable nonoperational structures,
15 analysis can involve identifying patterns in the data
that distinguish among the physically nonidentical
nonoperational structures. Also, relative physical
locations of nonoperational structures on the disc can
be calculated. A system for remotely analyzing data in
20 order to expedite complex data analysis and reporting
the results thereof is also provided.

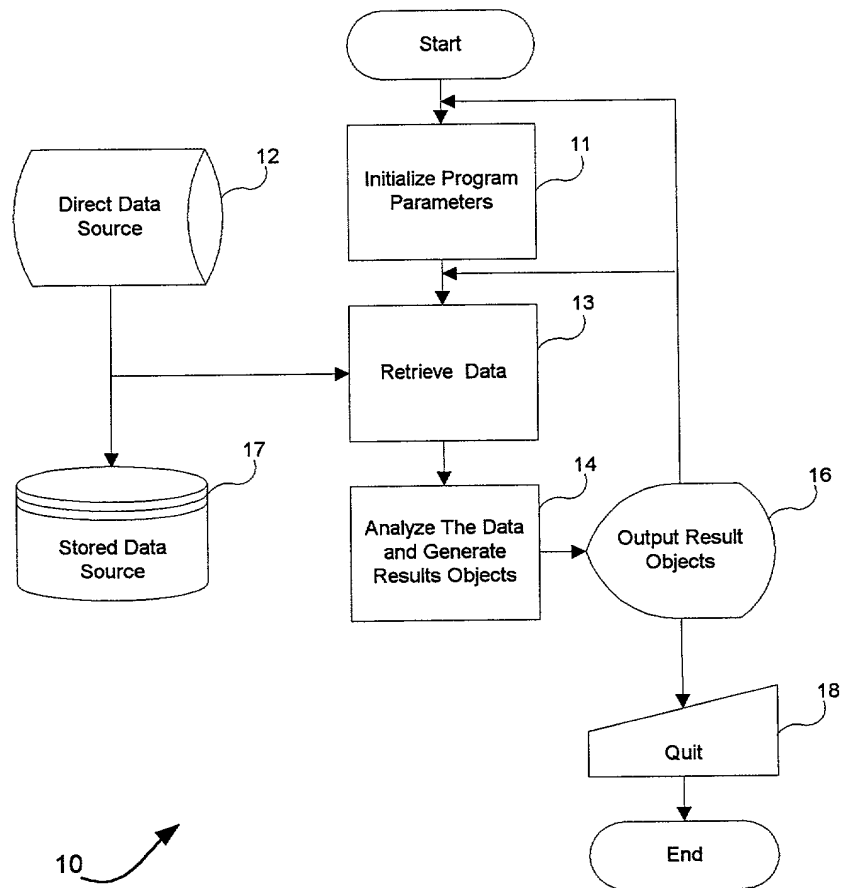


FIG. 1

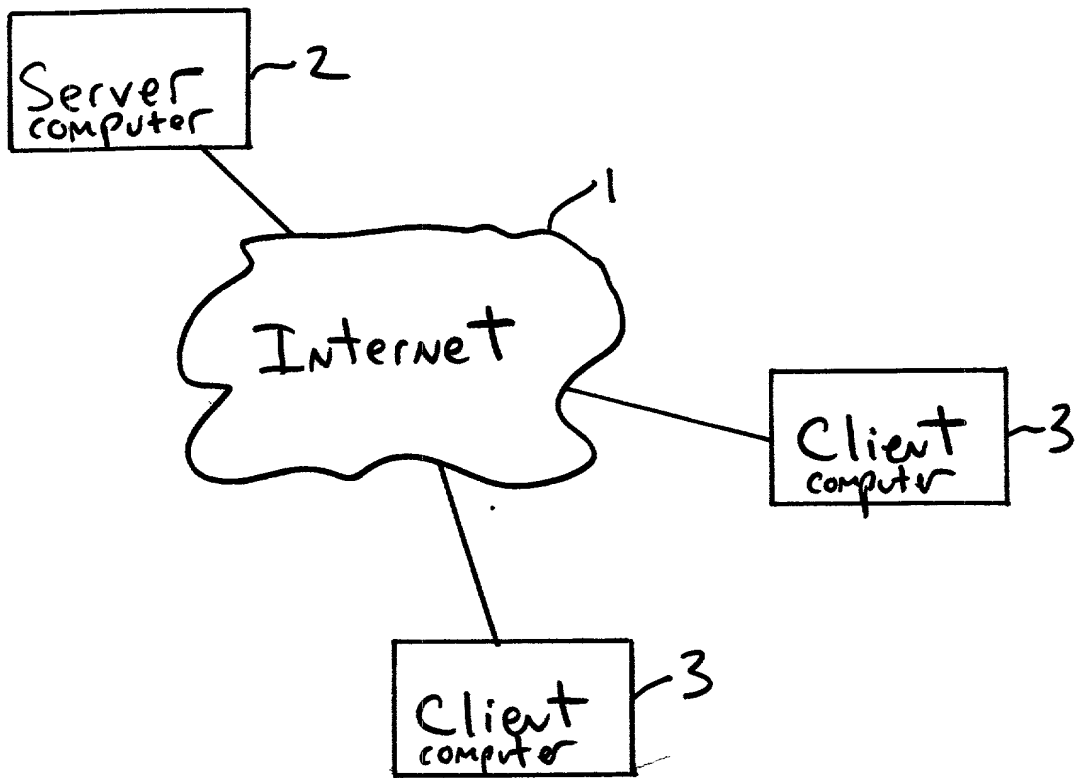


FIG. 1a

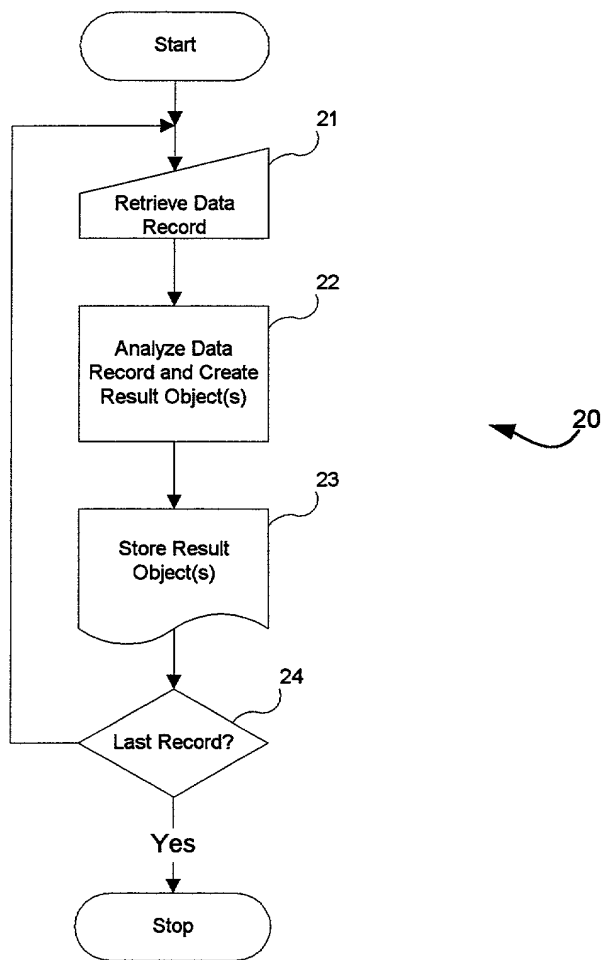


FIG. 2

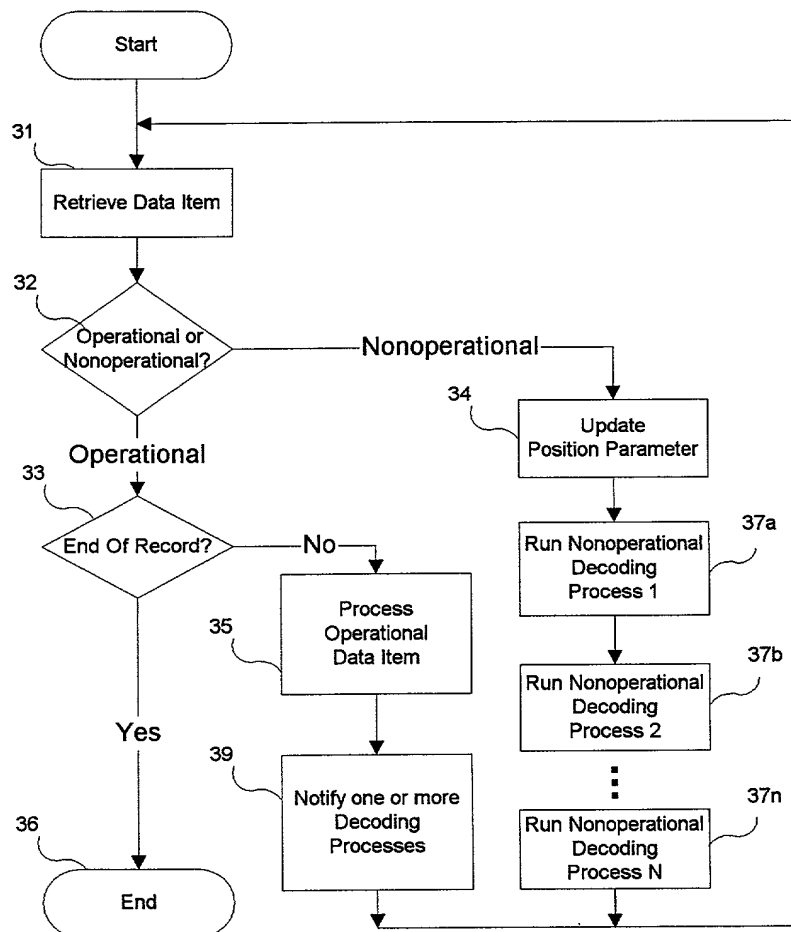


FIG. 3

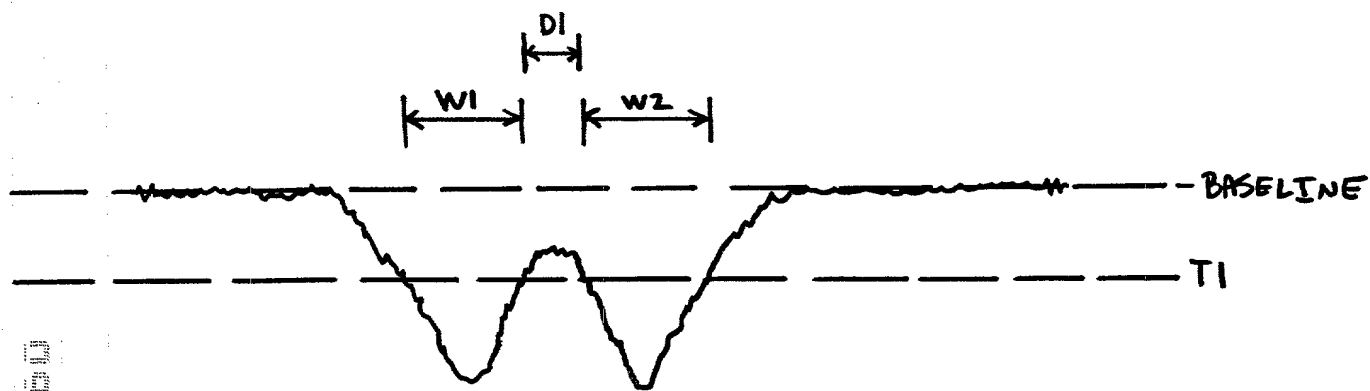


FIG. 3a

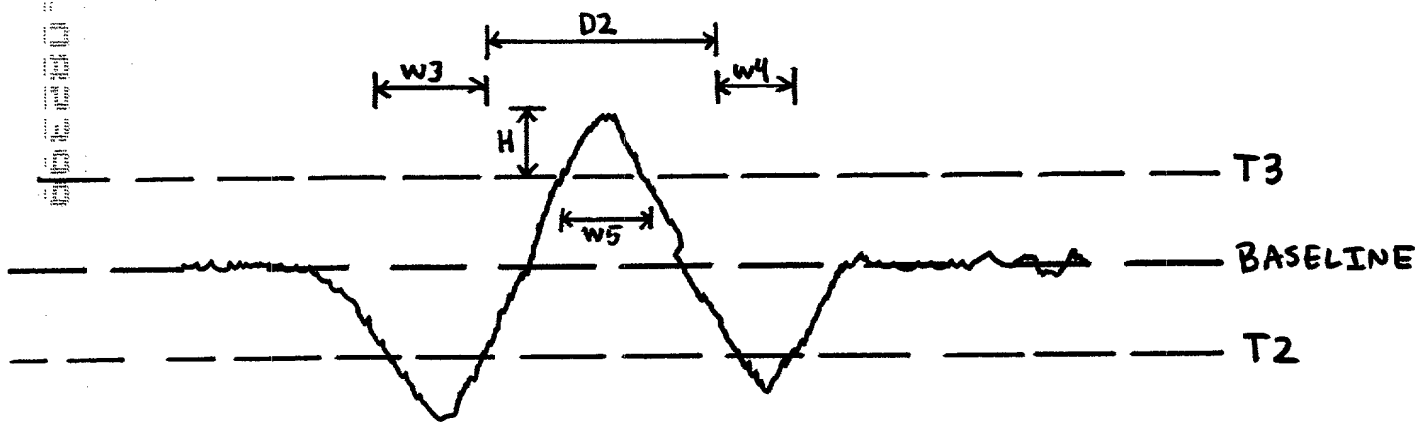


FIG. 3b

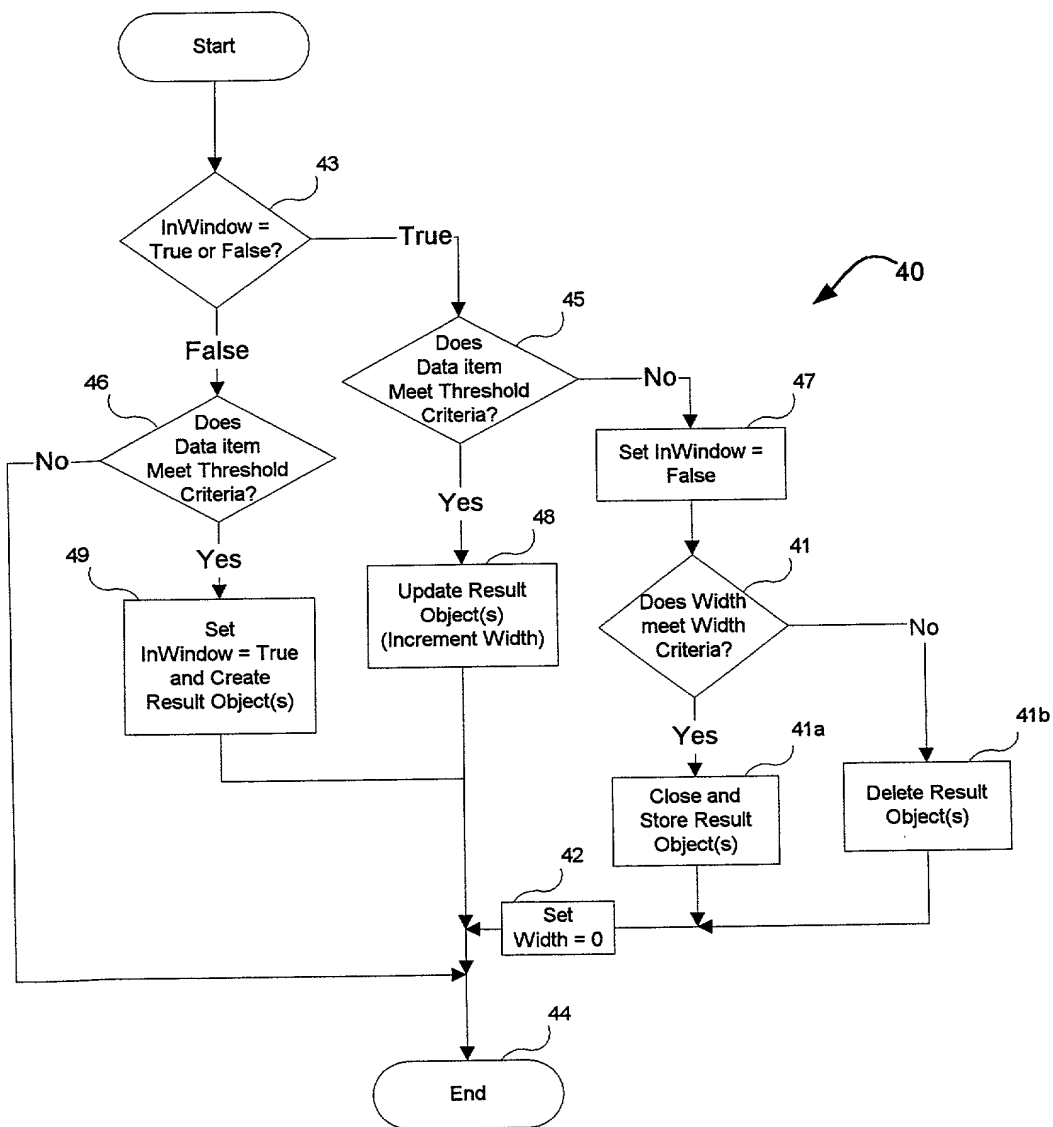


FIG. 4

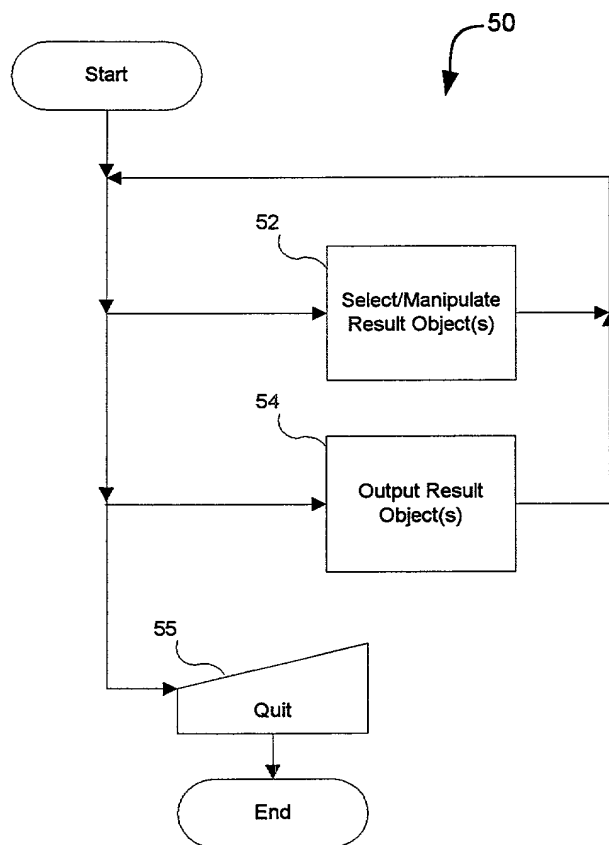


FIG. 5

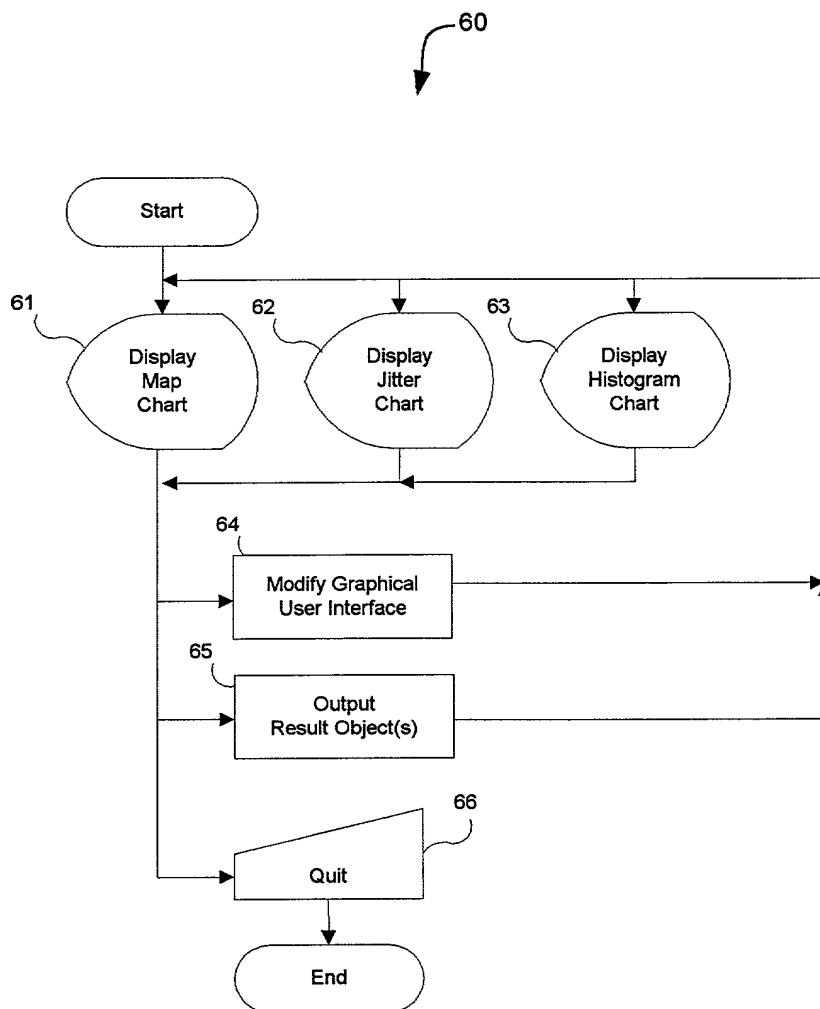


FIG. 6

560090.1

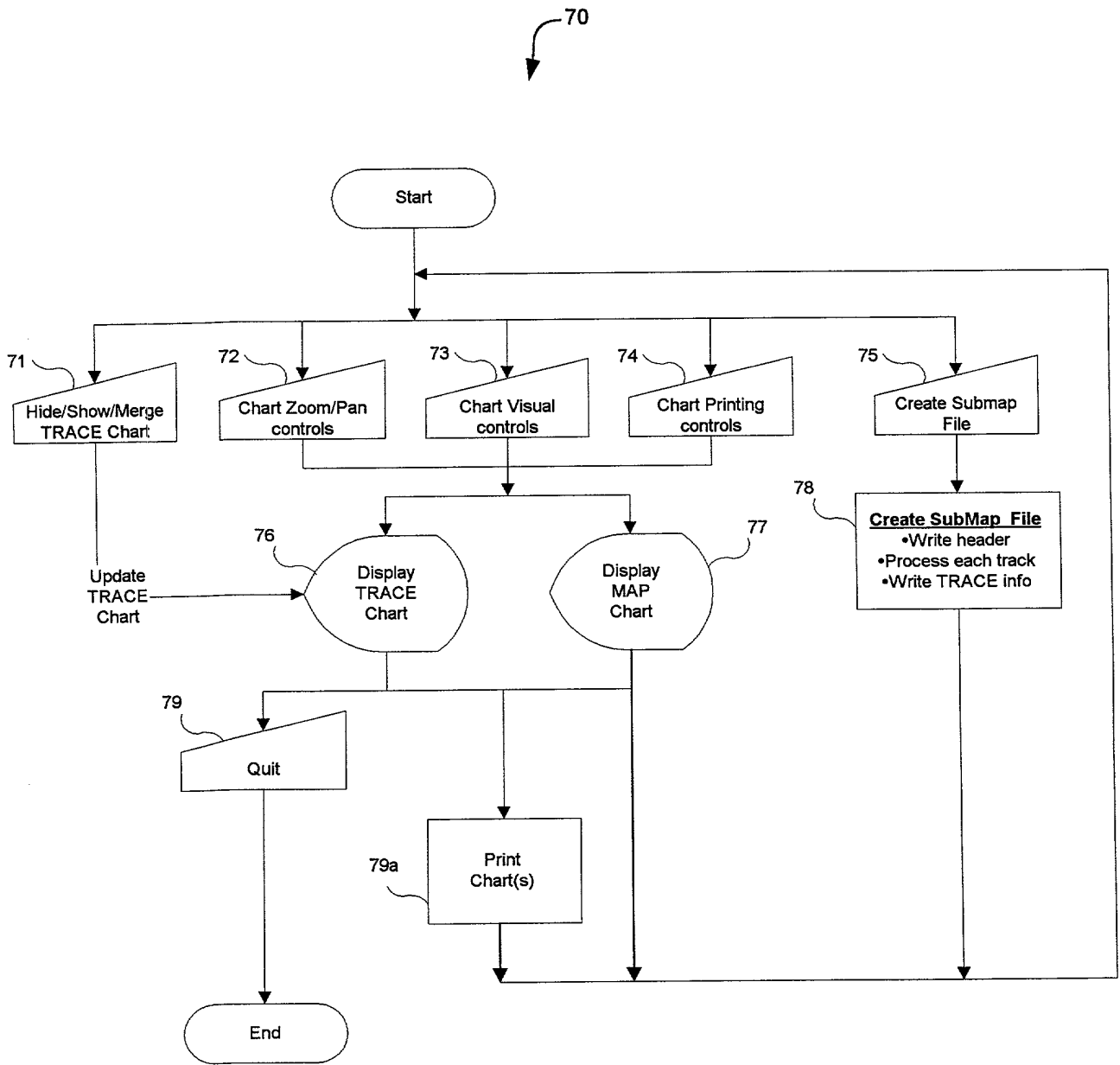


FIG. 7

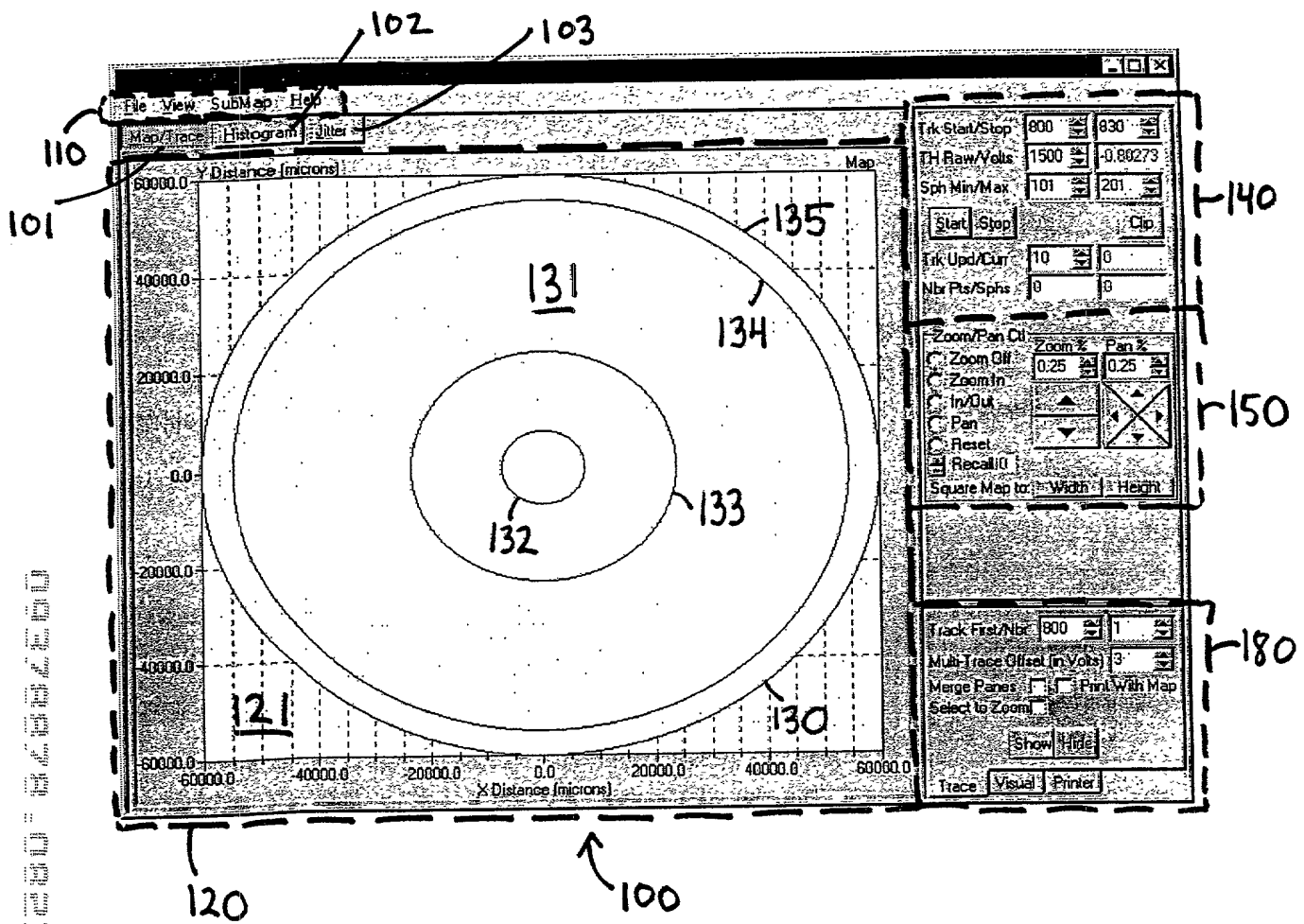


FIG. 8

Figure 1 is a screenshot of a "Debug Info" window. The window has a title bar "Debug Info" and a list of fields with their current values. The fields are: Trk Cnt/Nbr Pts (000), Nbr Pts/Sphs (0), Total Pts Read (0), File Position (0), Points Plotted (0), Points Skipped (0), Points Per Trk (0), Tot Pts Tested (0), and Difference (0). There are also checkboxes for "Starting", "Ending", "Passed", "Failed", "Hi", "Lo", and "Cnt Off". The window is labeled with various reference numerals: 170 for the window, 171a for the title bar, 171b for the first row, 172a for the "Trk Cnt/Nbr Pts" label, 172b for the "000" value, 173 for the "Nbr Pts/Sphs" label, 174 for the "0" value, 175a for the "Points Plotted" label, 175b for the "0" value, 176a for the "Points Skipped" label, 176b for the "0" value, 177a for the "Points Per Trk" label, 177b for the "0" value, 178 for the "Tot Pts Tested" label, and 179 for the "Difference" label.

FIG. 9

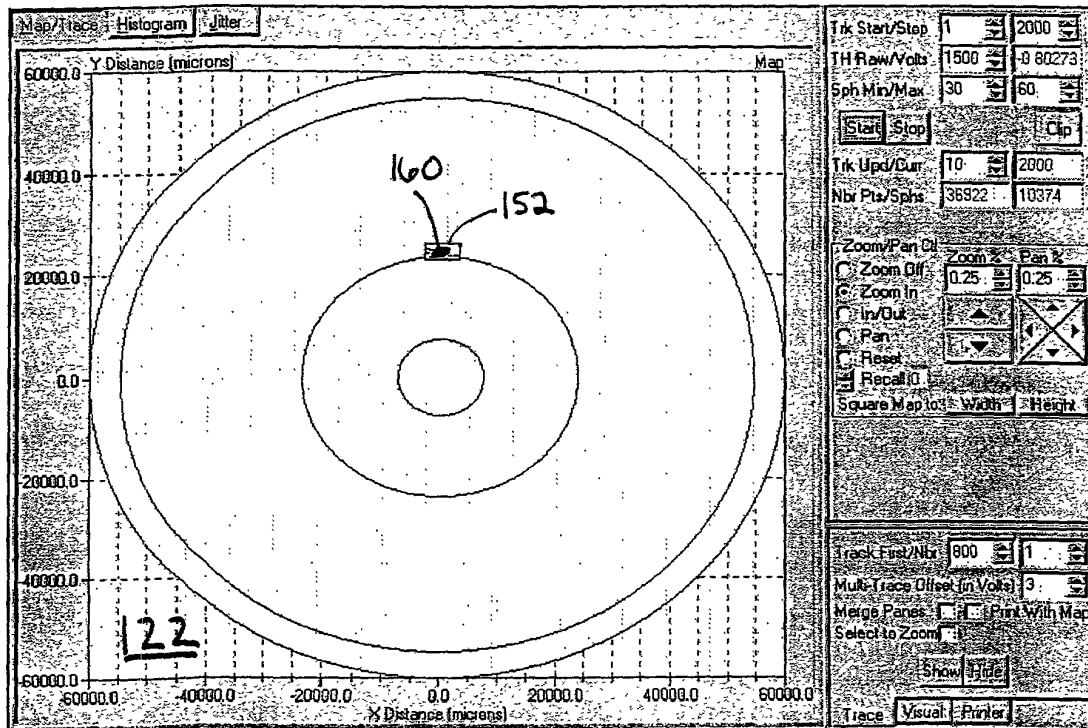


FIG. 10

FIG. 11a

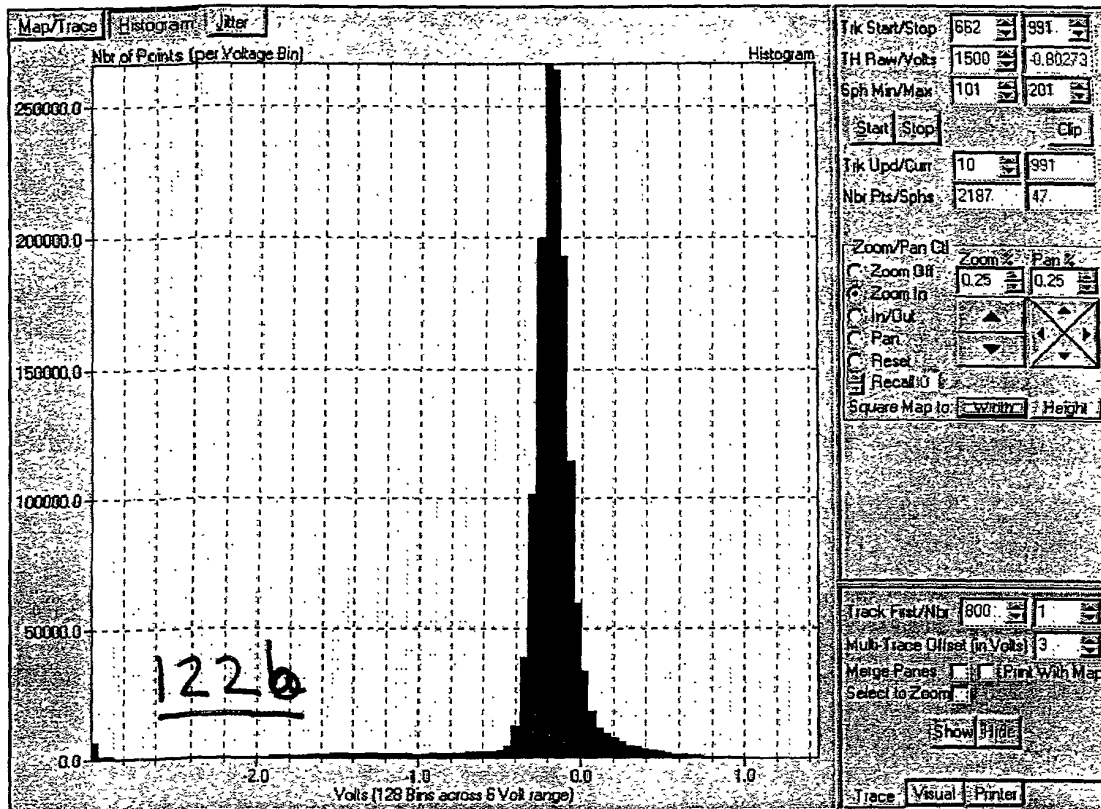


FIG. 12

00374878-002300

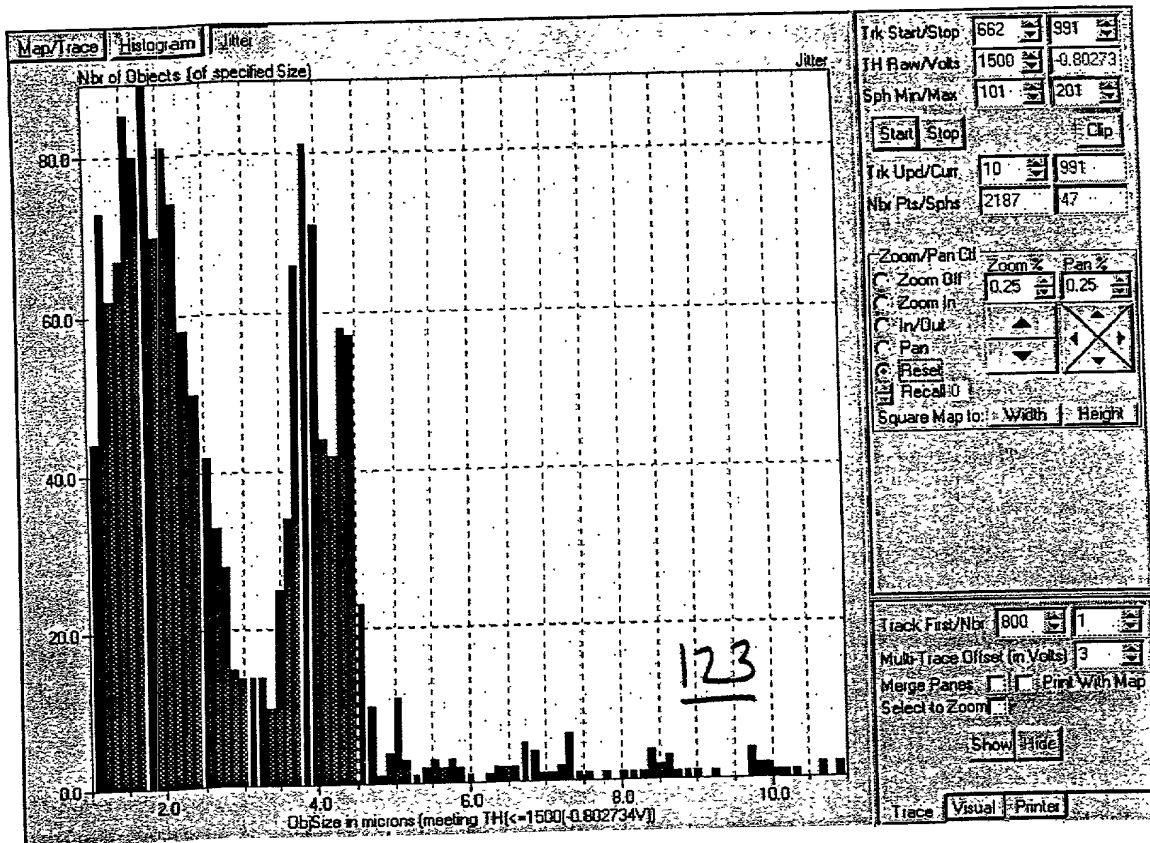


FIG. 13

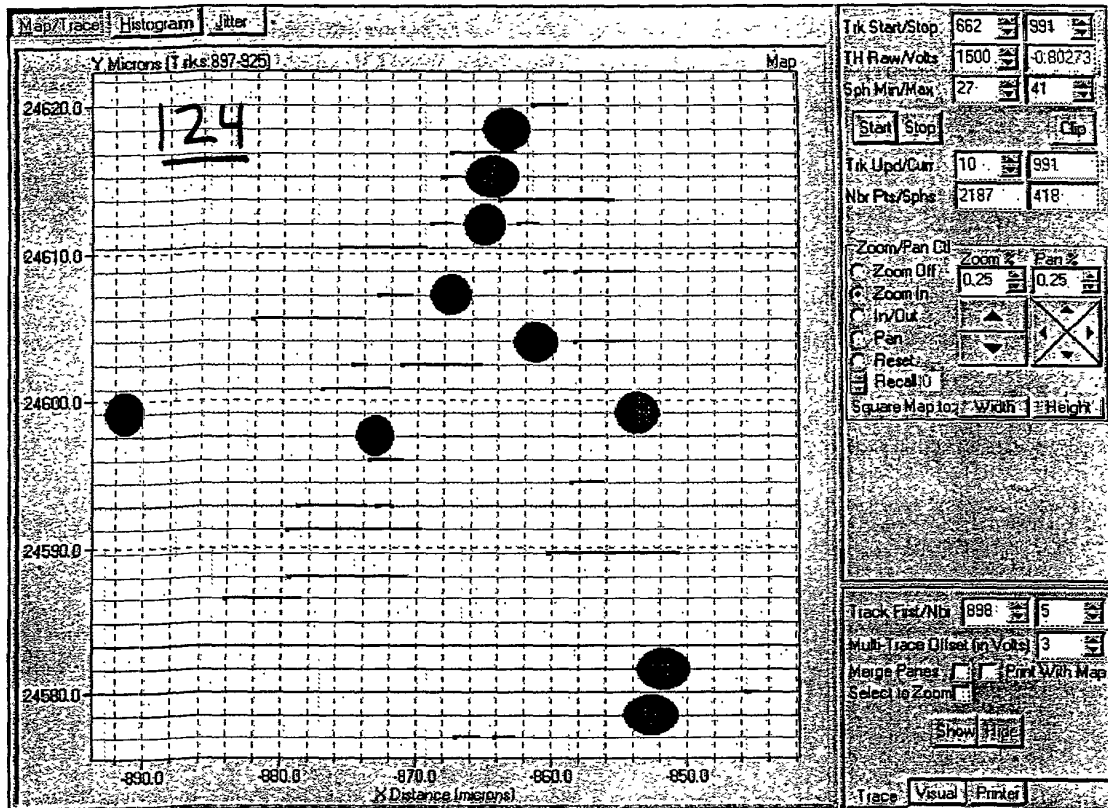
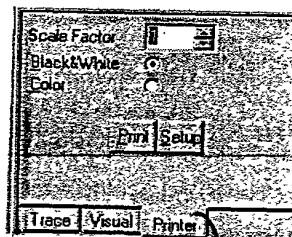


FIG. 14a



← 200

201

FIG. 14b

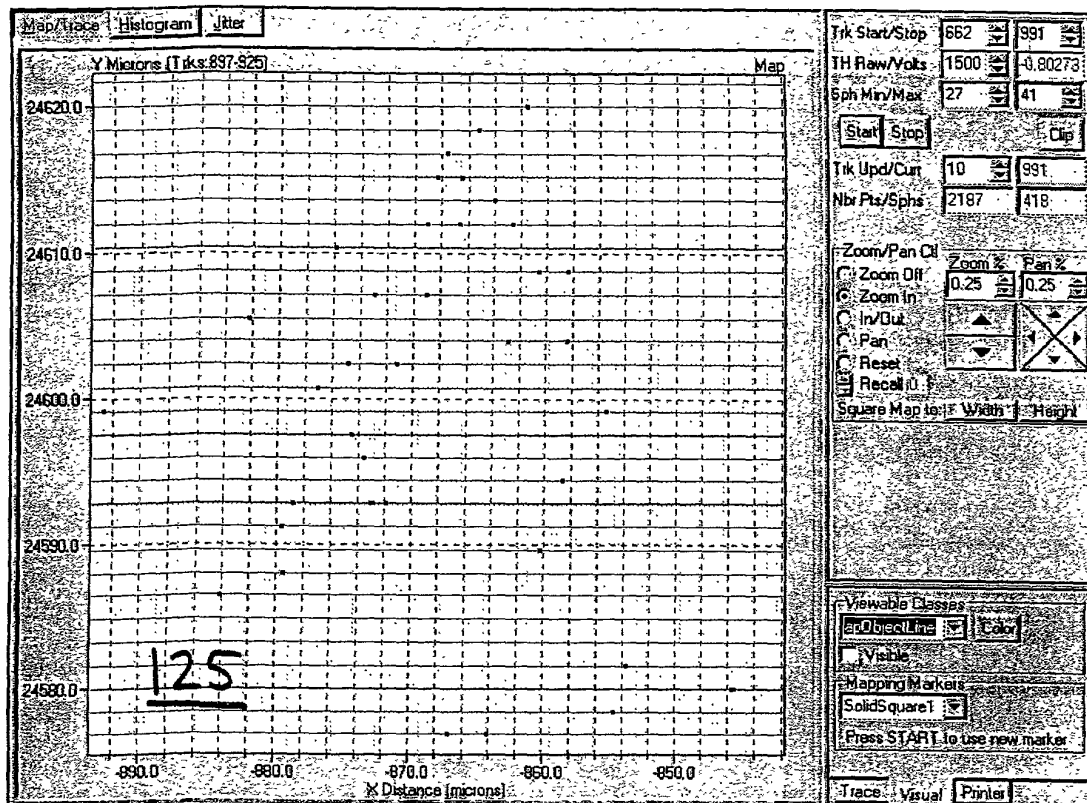


FIG. 15

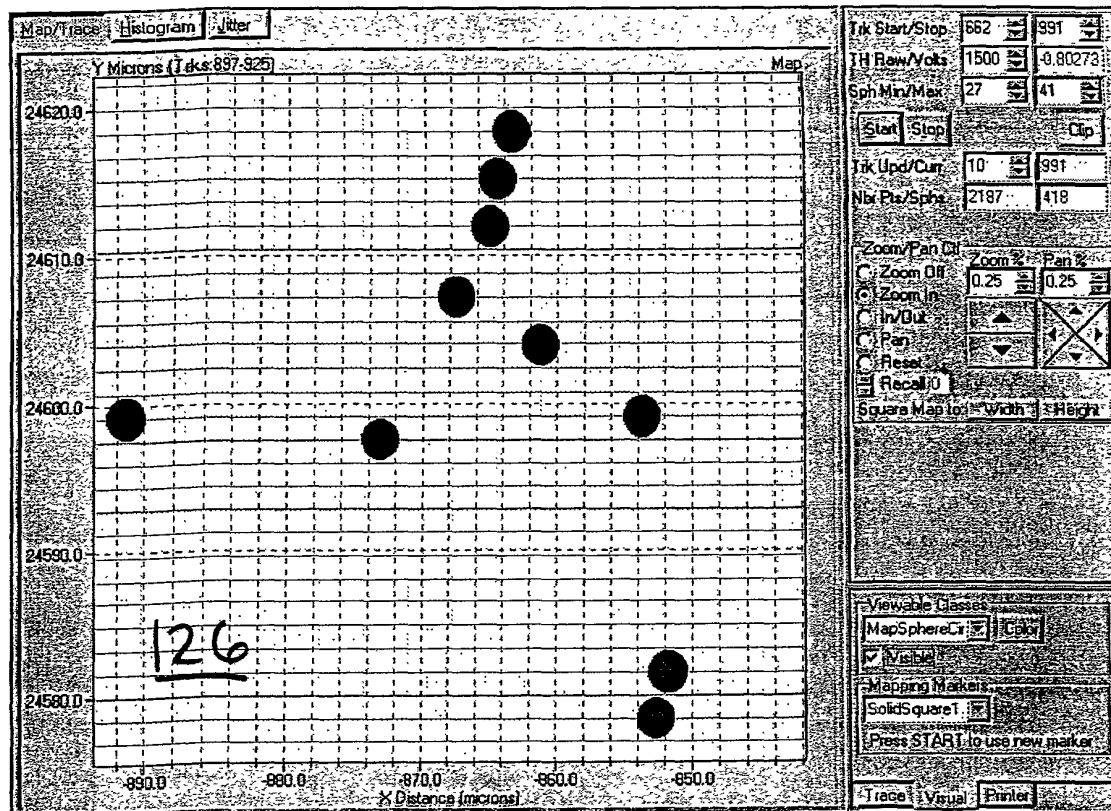


FIG. 16

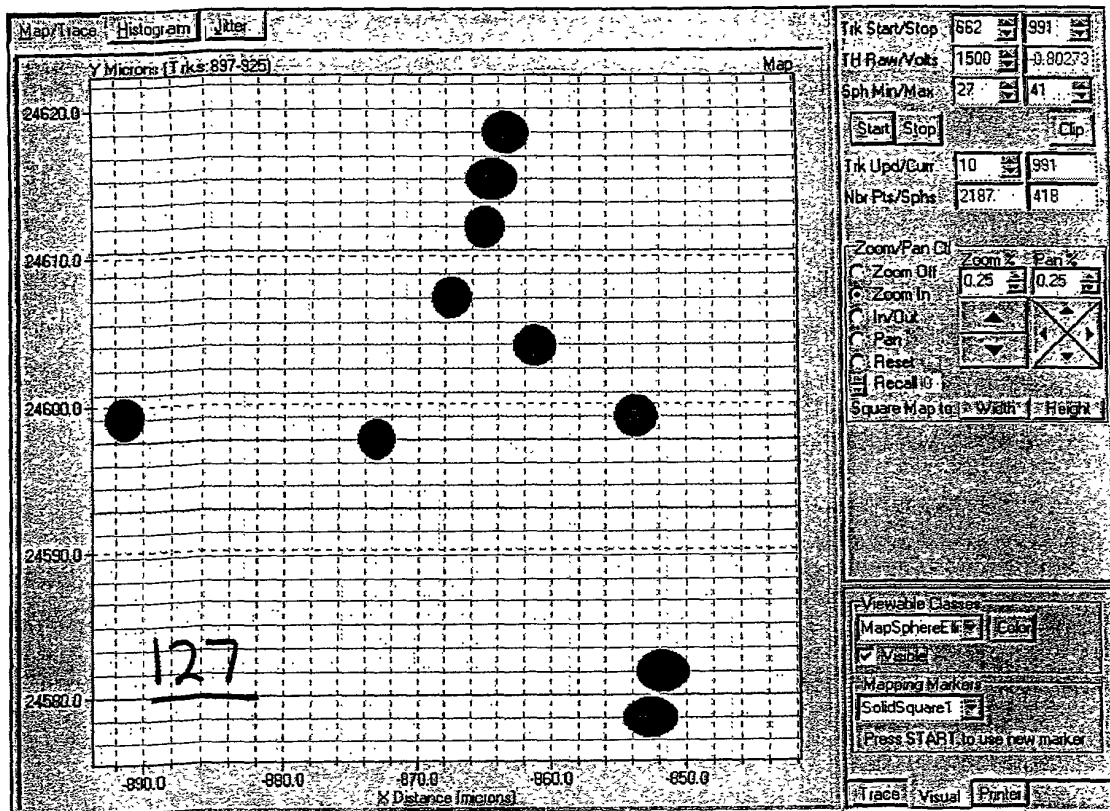


FIG. 17

The main display area shows a map of a surface with a grid. The vertical axis is labeled 'Y Microns (Trks:897-926)' and ranges from 24580.0 to 24620.0. The horizontal axis is labeled 'X Distance (microns)' and ranges from 990.0 to 950.0. A large handwritten number '128' is visible in the lower-left quadrant of the map.

On the right side, there are several control panels:

- Top Panel:**
 - Tik Start/Stop: 662 / 991
 - TH Raw/Vols: 1500 / 0:80273
 - Sph Min/Max: 27 / 41
 - Buttons: Start, Stop, Clip
- Second Panel:**
 - Tik Upd/Cur: 10 / 991
 - Nbr Pts/Spha: 2187 / 418
- Third Panel:**
 - Zoom/Pan Cl: Zoom Off, Zoom In, In/Out, Pan, Rese, Recall
 - Zoom %: 0.25
 - Pan %: 0.25
 - Navigation buttons: Up, Down, Left, Right, Center
- Fourth Panel:**
 - Square Map to: Width, Height
- Fifth Panel:**
 - Viewable Classes: MapSphereLi, Color
 - Mapping Markers: SolidSquare1
 - Press START to use new marker
- Bottom Panel:**
 - Trace, Visual, Printer

FIG. 18

Map/Trace Histogram Filter

Y Microns (Lake: 897.525) Map

24620.0

24610.0

24600.0

24590.0

24580.0

890.0 880.0 870.0 860.0 850.0

X Distance (microns)

129

Tik Start/Stop 682 991

TH Row/Vol 1500 -9.80273

Sph Min/Max 27 41

Start Stop Clip

Tik Upd/Cur 10 99

Nbr Pts/Sphs 2187 418

Zoom/Pan On

Zoom Off 0.25 0.25

Zoom In

In/Out

Pan

Reset

Recall 0

Square Map to: Width Height

Viewable Classes

MapSphereLi Color

Visible

Mapping Markers

SolidSquare1

Press START to use new marker

Trace Visual Printer

FIG. 19

The image displays two plots from a data analysis software, likely a scanning electron microscope (SEM) or similar instrument, showing spatial data and voltage traces.

Top Plot: Map

- Y-axis:** Y Microns (Trks 874-894), ranging from 24540.0 to 24570.0.
- X-axis:** X Distance (microns), ranging from 850.0 to 820.0.
- Features:** Two dark, irregular spots are visible, labeled **177a** and **178a**.

Bottom Plot: Trace

- Y-axis:** Voltage, ranging from -2,000 to 14,000.
- X-axis:** X Distance (microns), ranging from 850.0 to 820.0.
- Features:** Multiple stacked traces are shown. Several peaks are labeled with numbers: **172**, **175**, **177**, **176**, **174**, **179**, and **178**.

Control Panel (Right Side)

- Tik Start/Stop:** 662 / 991
- JH Raw/Volts:** 1500 / 1.80273
- SpH Min/Max:** 27 / 50
- Start/Stop/Clip:** Buttons for Start, Stop, and Clip.
- Tik Upd/Cur:** 10 / 991
- Nbr Pts/SpHs:** 2167 / 613
- Zoom/Pan Cl:** Zoom Off, Zoom In, In/Out, Pan, Reset, Recall 0.
- Square Map to:** Width, Height.
- Trace:** Visual, Printer.

FIG. 20

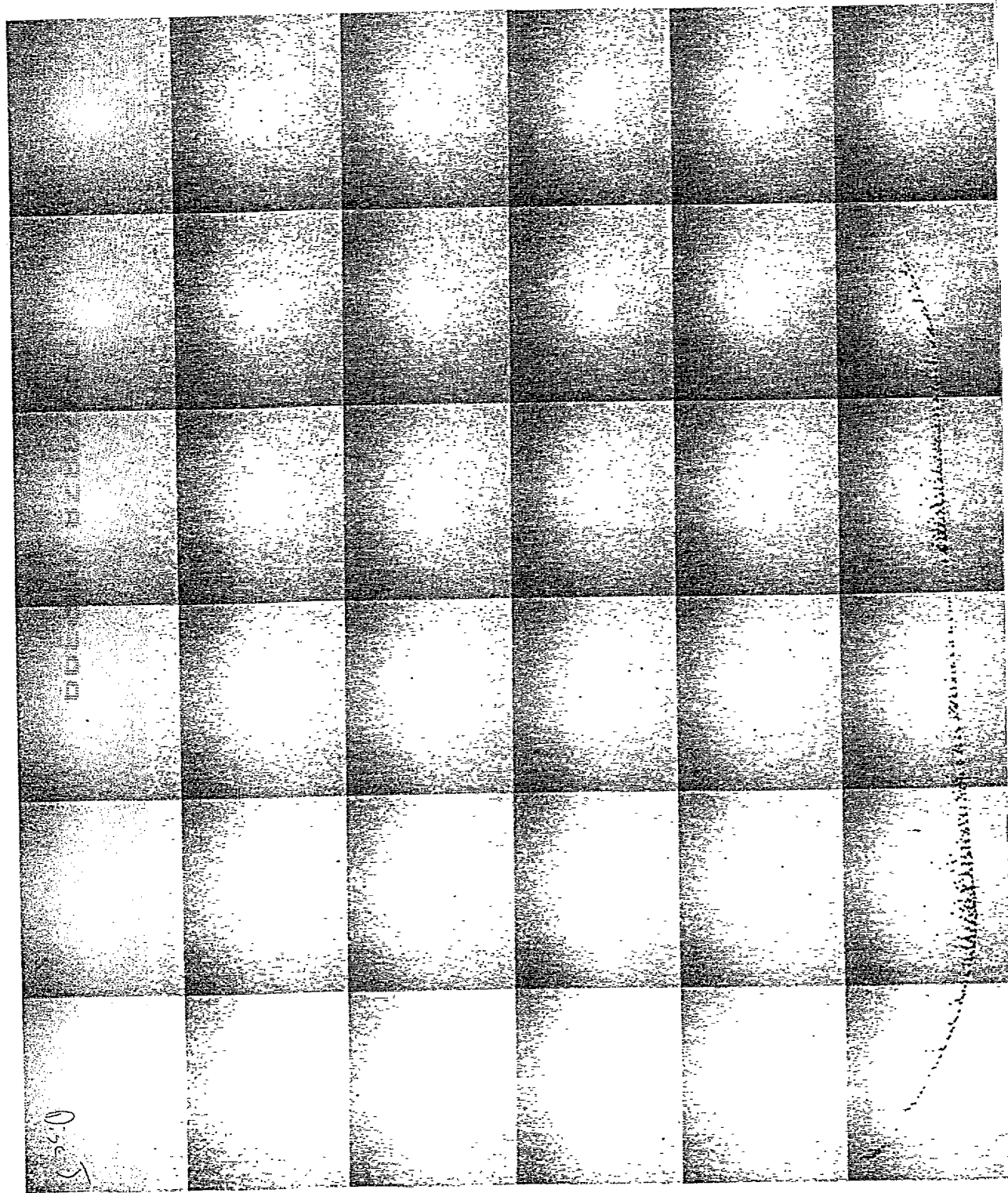


FIG. 21

A black and white photograph of a large group of people, likely a choir or a group of performers, standing in several rows on a stage. They are dressed in dark, formal attire. The background is dark and indistinct.

FIG. 22

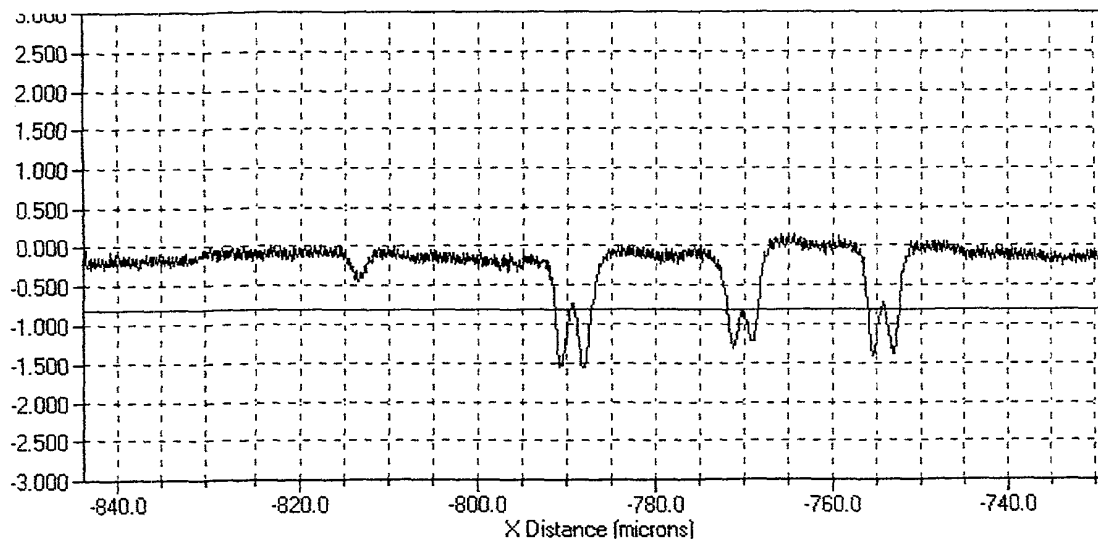


FIG. 23

FIG. 24

FIG. 27

FIG. 28

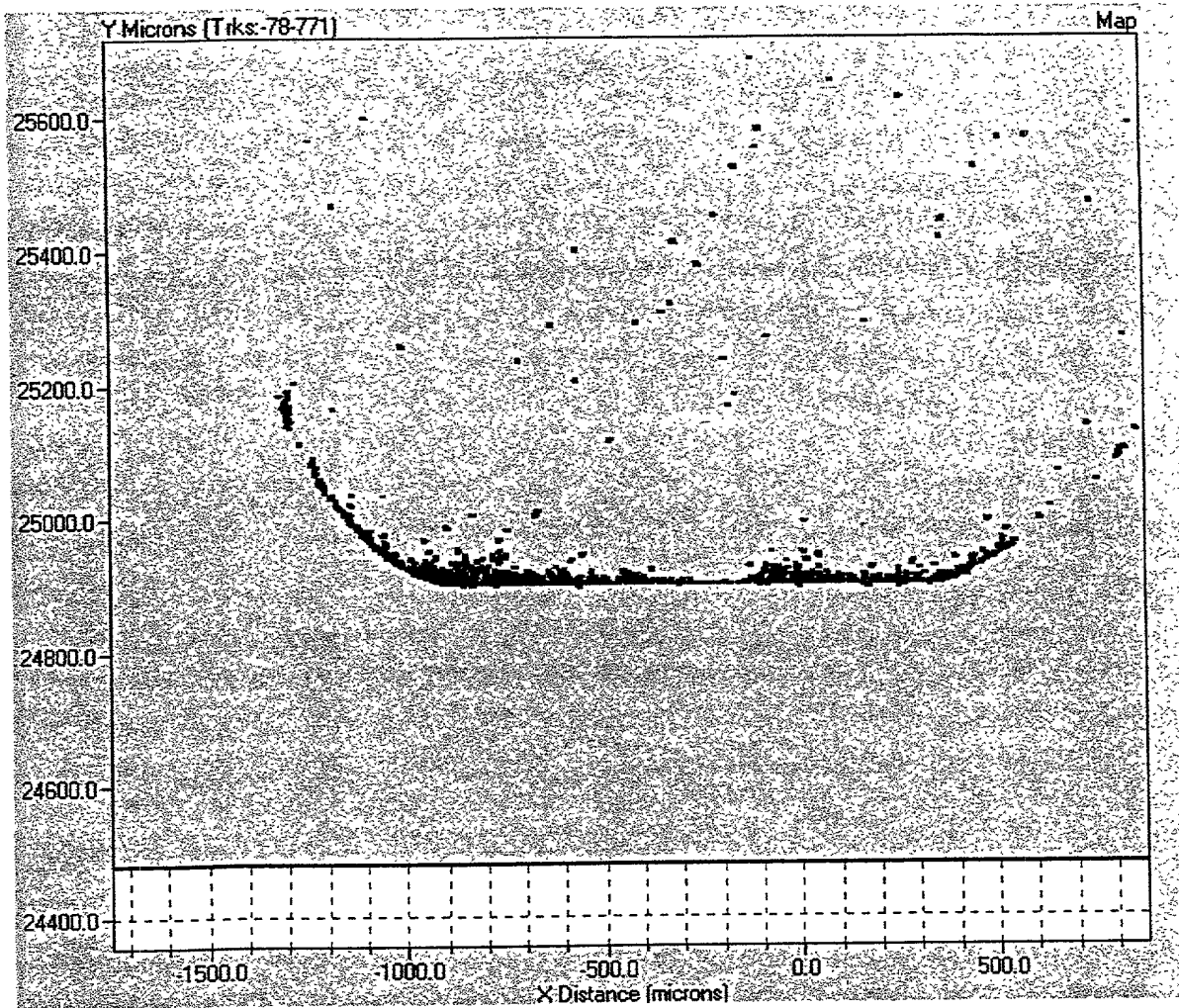
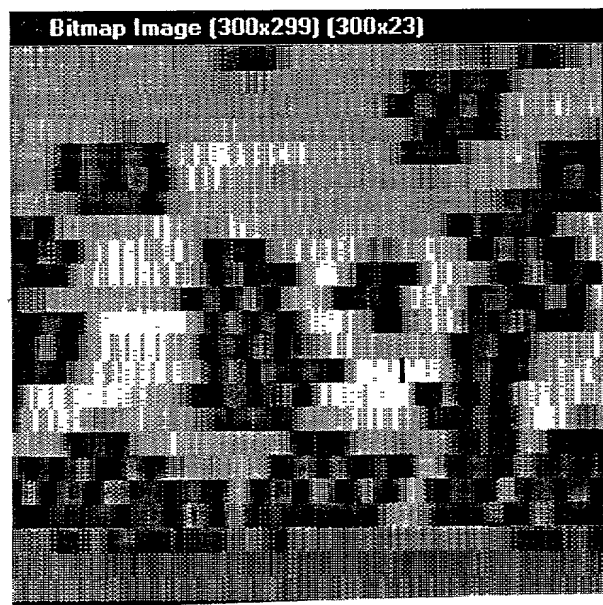
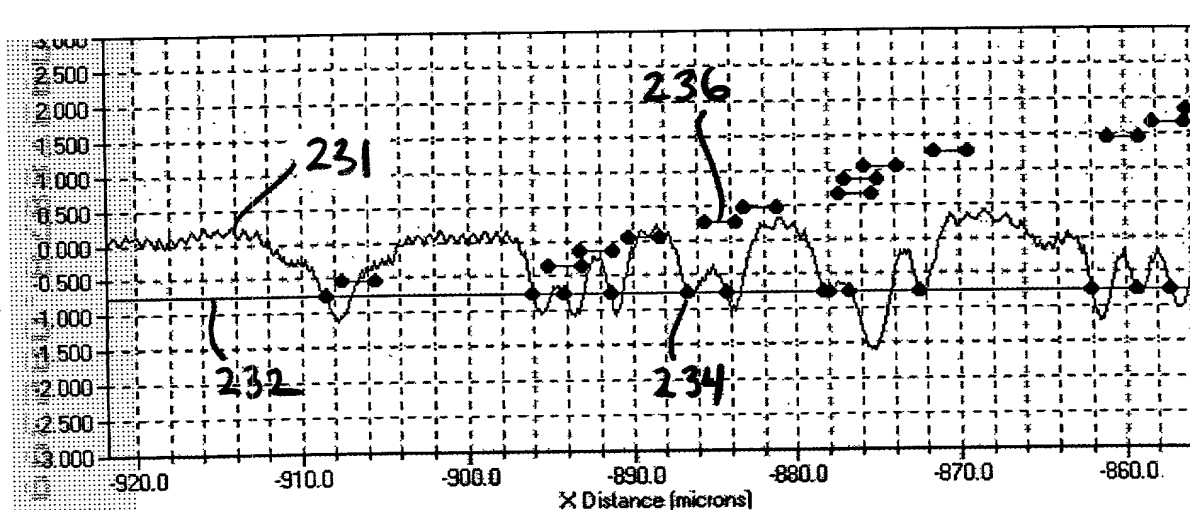
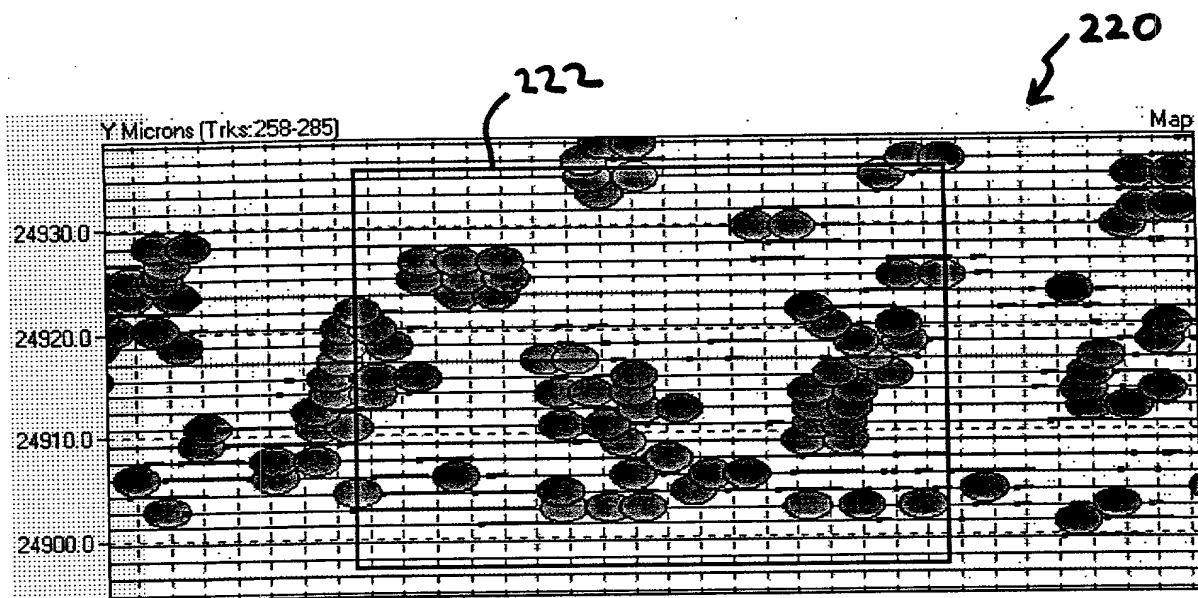


FIG. 29



EXPRESS MAIL LABEL
NO.: EH623266802US

BURST-15

DECLARATION AND POWER OF ATTORNEY

We, Mark O. Worthington and Gregory R. Basile, declare that we are citizens of the United States of America, respectively residing at and having post office addresses at 13841 Tustin East #183, Tustin, California 92780 and 2918 Maydelle, Farmers Branch, Texas 75234; and

that we verily believe ourselves to be the original, first and joint inventors of the invention or discovery in:

METHODS AND APPARATUS FOR ANALYZING
OPERATIONAL AND NONOPERATIONAL
DATA ACQUIRED FROM OPTICAL DISCS

which is described and claimed in the attached specification, and for which a patent is sought;

that we have reviewed and do understand the content of said specification, including the claims, and acknowledge our duty to disclose to the United States Patent and Trademark Office information known by us to be material to patentability as defined in Title 37, Code of Federal Regulations, § 1.56;

that we do not know and do not believe that this invention or discovery was ever known or used in the United States of America before our invention or discovery thereof, or patented or described in any printed publication in any country before our invention or discovery thereof, or more than one year prior to this application; or in public use or on sale in the United States of America more than one year prior to this application; that this invention or discovery has not been patented or made the subject of an inventor's certificate issued before the date of this application in any country foreign to the United States of America on an

application filed by us or our legal representatives or assigns more than twelve months prior to this application; and that no application for patent or inventor's certificate on this invention or discovery has been filed in any country foreign to the United States of America by us or our legal representatives or assigns;

and we hereby appoint

James F. Haley, Jr., (Reg. No. 27,794), Margaret A. Pierri, (Reg. No. 35,588), Hope Liebke, (Reg. No. 31,069), Jane T. Gunnison, (Reg. No. 38,479), Daniel M. Becker, (Reg. No. 38,376), and Brett G. Alten, Esq. (Reg. 42,258), our attorneys, with power of substitution, and with power of appointment of associate attorneys and agents, and of revocation of their powers, to prosecute this application and any divisions, continuations in whole or in part, renewals and reissues of the same, and to transact all business in the Patent and Trademark Office connected therewith;

and we request that communications be sent to:

Brett G. Alten
Fish & Neave
1251 Avenue of the Americas
New York, New York 10020-1104

and that telephone calls be directed to:

Brett G. Alten
(212) 596-9000.

Wherefore, we pray that Letters Patent be granted to us for the invention or discovery described and claimed in the attached specification and claims, and we hereby subscribe our names to the foregoing specification and claims, declaration, and power of attorney.

We declare, further, that we understand the English language and that all statements made herein of our own knowledge are true, and that all statements made on information and belief are believed to be true; and, further, that these statements were made with the knowledge

that willful false statements and the like so made are punishable by fine or imprisonment, or both, under Section 1001 of Title 18 of the United States Code and that such willful false statements may jeopardize the validity of the application or any patent issuing thereon.

Date _____

Mark O. Worthington

Date

Gregory R. Basile